20|20 Gen 3 Operator's Guide

Online Version

() IMPORTANT

This guide is intended for use with limited release software 2025.1.0 and its variants. Due to the nature of the limited release software update process, screenshots and descriptions provided in this guide may differ from the current version. Updates are made to this guide as often as possible. To download the most recent version of Gen 3 software, visit <u>2020.ag</u>

Contents

- General Overview
- Home Screen
- Fields
- Setup
- Products
- Equipment
- Systems
- Diagnose
- Calibrations
- Settings
- Appendix A

General Overview

This guide contains information on navigating the 20/20 Gen 3 monitor, understanding the information that it displays, and setting up basic equipment and systems. For detailed troubleshooting or specific Precision Planting product information, refer to all specific product operator's guides, or contact Precision Planting Product Support.

Hardware

The 20/20 consists of a Display Base Module [DBM] connected to at least one Display by an Ethernet cable. Other Ethernet devices may also be connected to the DBM.



The DBM Power over Ethernet [PoE] ports require a Shielded Twisted Pair [STP] CAT6 Ethernet cable to connect an Ethernet device to the DBM. The different Ethernet devices that may be connected to the DBM are the 10" display, the 16" display, the FieldView Module, and the Ethernet Switch.



Do not connect an Ethernet cable from an Internet access point to the Ethernet port on the DBM. Doing so will crash the access point. See **Connectivity** in the **Settings** section of this guide for information on connecting the 20|20 to an Internet access point.

Indicator Light Overview

Each Ethernet device utilizes a light to indicate device status. Use the following table to determine the status indicated by the light on the corresponding device.

Color	DBM	Display	FieldView Module	Ethernet Switch
		2 of 129		

Color	DBM	Display	FieldView Module	Ethernet Switch
Green	Powered On / Connected	Powered On / Connected	Powered On / Connected	Powered On / Connected
Solid White	Powering On	N / A	Downloading Software	Powering On
Blinking White	Firmware Updating	N / A	N / A	Firmware Updating
Solid Yellow	Preparing to Update Software	Initializing	Initializing	Initializing
Blinking Yellow	Software Update in Progress	Software Update in Progress	Software Update in Progress	Software Update in Progress
Blue	N / A	N / A	Not Connected to iPad	N / A
Purple	User must Power Cycle System	N / A	FieldView Cab App not Connected	User must Power Cycle System
Red	N / A	Powering On	Powering On	N / A
Blinking Red	Failure - Contact Support	N / A	N / A	Failure - Contact Support

Powering On / Off

The 20/20 requires 12 volts of key switched and constant power. Connect the display to the DBM, and the DBM to the power supply. If connected to a tractor or cab, turn the key to the on or run position. Press the DBM power button to the on position. To power the system off, press the DBM power button to the off position or key the tractor / cab off.

User License Agreement

License Agreement

Contents

- End User License Agreement
- · AGCO Privacy Statement United States & Rest of World
- AGCO Privacy Statement European Economic Area
- AGCO Machine Data Statement

End User License Agreement

Last Updated: February 6, 2019

This End User License Agreement (this "Agreement") is a legal agreement between (i) you (either an individual or a single legal entity), and (ii) Precision Planting LLC and its Affiliates ("we", "us" or "Precision"). By using the Precision Software, which can be products sold by Precision, you represent and warrant (a) that you are at least 18 years of age or the age of majority where you reside, (b) that you are acting for business purposes, and (c) that you have the power and authority to enter into this Agreement, and you agree to be bound by these terms and conditions, including Precision's Privacy Policy. If you are entering into this Agreement on behalf of a company or other legal entity, you represent that you can bind such entity, in which case "you" or "your" shall refer to such entity.

You must read the entire license agreement to continue.

Once the 20|20 has booted up, read and agree to the User License Agreement to use the 20|20. Agreement is required on first boot up, after a Delete All is performed, or when major software updates are completed.

(i) NOTE

If this system is being set up for a third party, reset the agreement to appear on next startup so the end user agrees to the document. Navigate to **Setup > Settings > About**, select *Agreements* and press *Reset EULA*.

Cab Control Module

All Precision Planting control products require a Cab Control Module [CCM] to be installed below the display. The CCM is connected using an RJ11 port located on the back of the display. If two displays are being utilized, only one display of the user's choice may have a CCM installed. The CCM will be auto-detected when connected properly.



The switch on the left-hand side is the Master Plant switch. For all control products to function the Master Plant switch must be in the up position. If it is in the down position, all control products will immediately be disabled. The three switches in the middle are swath section switches. Toggle these to the down position to swath off a rate section. If these switches are in the down position, the rows assigned to the switch will be shut off. The rows assigned to each switch may be configured by navigating to **Setup > Systems**, selecting the default Implement system, changing *Cab Control Module Mode* to *Custom*, and selecting a preset or custom number of rows to each switch. See **Implement (Default) System Settings** in the **Systems** section for more details.



The left and right swath section switches are also used to Autoload any systems which have the auto load function enabled. Raise both switches up for one second to load systems. Systems with autoload enabled will dispense product. This allows product to immediately be dispensed when beginning to plant / apply. To continue autoloading, lift and hold both switches. Product will continue to dispense as long as the switches are held up. $\frac{5 \text{ of } 138}{138}$

Safety Warning



If any control product is configured on the 20|20 display, the system will require a CCM and will prompt the user to toggle the Master Plant switch on the CCM before any control products may be used. This warning is triggered any time the system is booted up, and when the system has traveled for more than half a mile. If a CCM is not installed, press cancel to bypass this warning. No control systems will operate until the Master Plant switch is toggled. The Master Icon will be present in the top right of the 20|20 screen in the **Status Center** if the safety warning was bypassed and a control system is configured.

Home Screen

Overview

The Home Screen displays seeding and application data in an easy to read and navigate format. This information is presented as both metrics and high-definition maps. Additional screen configurations may be added and customized with different metrics, map sizes, controls, and bar charts. Screen configurations may be toggled between by pressing the arrows at the top of the screen.



Screenshots

To take a screenshot, press and hold in the upper right corner of the screen until the screen flashes white. This action may be performed at any time and in any menu of the 20|20. See **Data** in the **Settings** section for information on exporting screenshots to a USB drive.

Navigating the 20|20

In the different screens of the 20|20, there will often be a right and left window displayed in the center screen. The right window is typically used to view and select various settings, while the left window is typically used to make changes to the selected setting.

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When making changes to a setting using the left window, preset selections (e.g. toggling a setting between Enabled / Disabled) are automatically saved once pressed. When using a keypad to input values (e.g. editing preset population / rate values), it is necessary to press *Enter* to save the new value.

Home Screen Layout Tabs

Tabs are located at the top of the screen that may be configured to quickly change the layout of

the Home Screen. The only default tab layout is Large Map.

Up to eight total layouts may be configured and named. To configure new layouts, Press the *Four Squares* in the top left, then press *Layout +*.

Once new layouts have been added, pressing on a tab will change the layout of the home screen. Use the arrows or swipe left / right on the tabs to change which tabs are visible.

Any layout may be customized with different maps, controls, and metrics. See **Customizing the Home Screen** for more details.

Customizing the Home Screen

Press the Four Squares in the top left to enter Edit mode.

(i) NOTE

Only the active layout may be edited using this feature. To edit a different layout, press the *Checkmark* in the top left (while in Edit mode) to save current layout changes, then select a different layout. Press the *Four Squares* after selecting the desired layout to enter edit mode again.

Press *Settings* in the top right to rename or copy the active layout, or to reset all layouts. Press and drag on any layout to reorganize order.

After pressing the Four Squares, the Home Screen will be dimmed and overlaid with a grid which different control and metric widgets may be placed onto.

\bigcirc	<	Lar	ge Map	Editing M	j layout ap	Layou	t 🕀	>	Settir	ngs 😥	Cancel 🗵
					Dowr	Force					
					Margin Ibs						
					Ground Contact	% ↑					
								-			
										Add Widge	et 🕀

Press *Add Widget +* in the bottom right to add new widgets to the Home Screen.

There are four types of widgets: Metrics, Controls, Dashboard Minichart, and Maps.

Different sizes are available for each type of widget. Widgets are not always available in each size. The Map widget may be sized to any desired height and width.

Add Widget To: Control Cancel (8)									
Metrics	Controls	Dashboard	Minichart		Мар				
Population – – K/ac Master Off ↓ ↑	Good Spacing % +	SRI 	Singul: 	ation % ↑	Small				
Vacuum 0.0 in H2O 0.0 0.0 ↓1 0.0	Closing Margin 16.5 lbs Ground Contact 100 % ↓ 4 13.0 18.0 6 ↑	Down Force Margin 0.0 lbs Ground Contact 0.0 % ↓ 1 0.0 1.00 6 ↑	Nitrogen gal/ac Not Applying ↓ ↑		Wide Tall				
Insecticide Magnitude Not Applying ↓ ↑ CEC	Insecticide Uniformity % ← Clean Furrow	Insecticide Ibs/ac Not Applying ↓ ↑ Furrow Moisture	Good Ride 100 % 100 100 1 ↑ Organic Matter		Large				

() INFO

Every Precision Planting control or sensing product requires a Control widget to be placed on the Home Screen. The product will not function and cannot be calibrated until the corresponding widget is placed and enabled.

If any part of a new widget is placed on top of an existing widget, the entire existing widget will be removed.

After a widget has been set in place, press *Add Widget +* again to continue customizing the layout. After customization is complete, press the Checkmark in the top left to save the current layout.

Dashboard Mini-Chart and Metric Screen

The Dashboard Mini-Chart [DMC] may only be placed at the bottom of the screen. The DMC displays a row-by-row bar chart for one of the metrics measured by the 20|20 for each row. Good row bars will be green, Alarm row bars will turn yellow, while Failure row bars will turn red. A scale showing numerical values is displayed in the lower right corner. See **Systems** for more details on adjusting Alarm and Failure thresholds.

Large						
Population						
28.0 K/ac						
28.0 28.0						
↓2 28.0 28.0 1 个						
Down Force						
↓3 57.0 82.0 1 ↑						
Closing						
Margin 16.3 lbs						
Ground Contact 100 %						
↓ 4 13.0 17.0 1 †	@imapbox	2-25-180	-	<u> </u>	inac	
33.0 K/ac 28.0 K/ac					Population	
23.0 K/ac -					😂 s	etup

Rows that are swathed off will show yellow under the bars on the bottom line of the DMC.



The name of the active metric shown on the DMC is displayed above the Setup button. To change $$11\,\mathrm{of}\,138$$



the metric, press on the active metric name to open the **Metric** screen.

The Metric screen displays a more detailed row-by-row chart. Press any option on the right to view the row details screen for the selected system metrics. Scroll on the menu to view all available options. For applicable metrics, use buttons at the bottom of the screen to scroll between rows or to select a specific row.

↑ DMC Configuration ► See	ding			\triangleright	5.6 mph 10:3	6 pm ∢••>
Population >	28.0 K/ac	Good Spacing		100 %	III DMC Configurati	on
30.0 K/ac		101 %			Implement	
15.0 K/ac		101 %			Seeding	-
0.0 K/ac 30 sec 15 sec	0 sec	100 % 30 sec	15 sec	0 sec	Population	
Average Spacing >	7.47 in	SRI >		0.0%	Good Spacing	
9.50 in		1.40 %			Average Spacing	
8.25 in 7.00 in		0.700 %			SRI	
8 sec 4 sec	0 sec	30 sec	15 sec	0 sec	Singulation	
Doubles >	0.00%	Skips >		0.0%	Vacuum —	
1.00 %	Viewing	1.00 %	Row 2			
	Viewing				📊 Home	

Press *DMC Configuration* in the upper right to toggle DMC Auto Scroll on or off, or to adjust the scroll frequency that the DMC will use when cycling between metrics. If Auto Scroll is set to single, change the displayed metric by selecting it in the table in the right window.

↑ DMC Configuration	on		\triangleright	5.6 mph & IIII	10:37 pm
DMC Auto Scroll Settings		DMC Chart		II. DMC Con	figuration
DMC Chart Enabled	Auto Scroll 6 charts	Single	Auto Scroll	Implement	
Auto Scroll Delay	5 seconds	Population	Good Spacing	Seeding	
		Average Spacing	SRI	Closing	
		Singulation	Vacuum	Down Force	
		Closing	Down Force	Nitrogen	
		Nitrogen	Insecticide Magnitude	Insecticide	
		Insecticide Uniformity	Insecticide	Row Cleaner	
		Good Ride	Row Speed	Depth 🔶	• •
				n Ho	ome

13 of 138

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The **Metric screen** may also be accessed by pressing the corresponding widget (e.g. Singulation) on the home screen, or pressing the DMC directly.

Hybrids

Hybrids are displayed below the bar chart. The hybrid name in the lower left screen will alternate between hybrids if multiple are active.



Manual Swath Control

A Swath Control Bar may be added to the home screen instead of the DMC. The swath control bar may be used to manually swath on / off any rows for all systems which the 20|20 is controlling.



(i) NOTE

The Swath Control switch on the CCM must be in the Up position to enable manual swath control.

Press and hold on any row in the Swath Control Bar until it turns yellow to swath that row off. Press and drag across multiple rows after the initial row turns yellow to swath off multiple rows.

	<		Large I	Мар		L1		Control		Widg	ets	>	5.6 mph	10:39 pm •••
	Popul	ation		= Equipm	ent-Wide						Split	[-]-]	Down Force	
		K/ac		- Cove	rage						opin		Master Off	Enabled
N	/laste	er Off		Show									Closing	
+			+										Master Off	Enabled
- 1	Down	Force										R N	Insecticide	
Margin		0.0 lbs										#	Enabled	Disabled
Ground Co	ontact	0.0 %						-					Depth	
4 3	-1.0	1.00	6 🕇									<u>₽</u>	Master Off	Enabled
	Clos	sing											Swath Contr	ol
Margin		16.3 ⊮	s									(\pm)	Man	ual
Ground Co	ontact	100 %						-				\bigcirc	Quick Start	
↓ 4	13.0	17.0	1	mapbox	0	1		2-25-180		2 miles		<u> </u>	Inac	tive
Good			07	SDI		9/	Organic	5 00	97	Insecticid	e		2-25-180	
Spacir	ng		/0	JKI		/0	Matter	3.90	70	Magnitud	e		2025	Corn
Res	et		1	2		3				5 6		🖳 Setun		
Reset 1			_				4					Setup		

Swathing off any row manually will engage Manual Swath Mode. In Manual Swath Mode, the 20|20 will no longer swath off to boundaries or coverage. To return to Automatic Swath Mode, press *Reset* in the lower right corner.

() INFO

The Swath Control Bar is also displayed on the Control screen for any control system, and on the Swath Control screen. See **Swath Control Screen** for more details.

Control Screens

Press on any Control widget to open that system's **Control Screen**. Use the Control Screen to enable the system, select a rate for single / multiple rate sections, change from manual to prescription or sensor control, edit prescriptions, access the **Swath Control** screen, or prime the system.



(i) NOTE

Orange Tank / **Blue** Tank options on all screens of 20|20 will only be available if a multi-hybrid seeding control product (mSet / vSet Select) is configured.

Single Rate Section

Enter a rate for the entire system by pressing the -- under **Seeding Target** to enter a manual rate. Use the *+(value) / -(value)* buttons in the top center to adjust the rate by the indicated amount.

Presets

When using single rate section control, a table of presets is displayed in the center to allow the user to quickly switch between populations. Change these values by pressing *Edit Presets* on the right.

Multiple Rate Sections

Set **Rate Section** to multiple to set up multiple populations / rates for each rate section. Use the +(value) / -(value) buttons in the top center to adjust the rates for all sections by the indicated amount. Multiple rate sections must be configured in **Systems** to use this feature. See **Other Systems** in the **Systems** section of this guide for more details.



Prescription Control

Select *Prescription* under **Control Mode** to use a prescription file to control rate. A map of the prescription will be displayed in the center. Press *Edit Prescription* on the right to edit zone rates for the prescription.



() IMPORTANT

Prescriptions must be imported into the 20|20, and assigned to the active field before the user may enable prescription control. See **Field Setup** in the **Fields** section and **Import Data** in the **Settings** section to learn about importing and assigning prescriptions.

Edit Prescripiton Screen



Select the desired attribute to edit using the dropdown box above the map, then select the desired zones rates and use the buttons at the bottom to adjust those rates by a percent or by a preset value. Press *Adjust Unit of Measure* to switch between Imperial and Metric measurements for the selected zones.

Sensor Control

↑ Seeding Control				(>])	3.0 mph ℭ IIII	10:45 pm
SEEDING CONTROL	SEEDING TARGET					E Seeding	Control
Enabled Disabled	\$ 28,000	seeds/ac	⊖ 500	(+) 500		edit Pres	ets
RATE SECTION Single Multiple	28,000	30,000	+ OM >	d		ዂ Swath Co	ontrol 🛛 🕨
CONTROL MODE	22.000	26.000		u		🕅 Edit Pres	cription
Manual	32,000	36,000	Active Disabled			 Prime Sy	stem
Prescription	100,000	110,000					
Sensor	120,000	130,000					
1 2	3	4	5	6			
$\langle \rangle$	Swath Auton	natic 🔒	<	\rightarrow		n H	ome

Some control systems may be configured to use a sensor to control rate. Sensors include SmartFirmers and Vision cameras. This guide details SmartFirmer sensor control setup. Refer to Vision documentation for information on setting up camera sensor control.

OM/CEC Control

Select *Sensor* under **Control Mode** and press **OM** or **CEC** in the center to configure either **O**rganic **M**atter or **C**ation **E**xchange **C**apacity control parameters.

∱ ▸ Seedin	g Control ► OM			0.0 mph	2:34 pm
	Orange Tank	Blu	ue Tank	Settings	
OM Max	OM Min	% Of Target Rate	Adjustment Range		
100%	5.00%	105%	Current Target	30,000 se	eds/ac
5.00%	4.00%	105%	OM Max		1 00 %
4.00%	3.00%	100%			1.00 %
3.00%	2.00%	95.0%	OM Min		0.00 %
2.00%	1.00%	90.0%	Percent of Target	90% 27,000 se	eds/ac
1.00%	0.0%	90.0%			_
Del	ete Last 🚃	Add Adjustment			
		Do	one 🕢		

Select a **Range** in the left window, then use the settings in the right window to set values and desired rate for that range. To fine-tune control, press *Add Adjustment +* in the lower left window to add another range. Each range must be configured manually. Use the **Settings** tab at the top to toggle OM / CEC control between Enabled and Disabled.

(!) IMPORTANT

It is required to add a max value of 100% to the first range, and a min value of 0% to the last range as "control layers" for the system. The max value of each range must be equal to the min value of the preceding range. See the above image for correct control layer setup.

Moisture Control

↑ Depth Control ► Moisture				mph	2:23 am � ↔→					
Adjustments		Settings								
Moisture % Adjustment		Maximum Moisture (Too Wet)								
Current Target	2.50 in		38	nn	%					
Minimum Depth (Wet)	2.00 in									
Maximum Moisture (Too Wet)	38.00 %	7	8	9						
Minimum Moisture (Too Dry)	34.00 %	4	5	6						
Maximum Depth (Dry)	3.00 in	1	2	3	-					
		0	00	000	•					
Enter ⊘										
	Done 🥥									

Use the right window to select moisture control parameters for SmartDepth and edit the selected values using the left window. **Minimum Depth** is the planting depth that the system will adjust towards when readings approach or exceed **Maximum Moisture** value. **Maximum Depth** is the planting depth that the system will adjust towards when readings approach or exceed the **Minimum Moisture** value. Use the **Settings** tab at the top to toggle Moisture Control between Enabled and Disabled. The system will control to the **Current Target** whenever sensor control is disabled.

Priming the System



Press *Prime System* on the right to access the **Prime System** function. Press *Prime System* at the bottom of this screen to open a popup which instructs the user to hold both switches up to dispense product at the system's default rate. The system will dispense as long as the switches are held up.

(i) NOTE

Product will only be dispensed for the specific system through which the Prime System function was accessed.

Controlling a Second Display

Three **Large** control widgets are available which may be used to control map or layout features of another display that is connected to the same DBM. This feature may be useful when one display is mounted in a hard-to-reach area of the cab.

Add Widget To: C	ontrol					Cancel 🛞
Metrics Contr		Dashboard Minichart		l Minichart		Мар
				Row Cleaner Master Off Target Adjust () 10.0	 20100019 20100019<	Small Wide Tall
Map Layers 70100019	Active Layout 70100019 Control					Large XL

The number in the top right of each widget indicates the serial number of the display that the widget will control.

- Map Controls Sets map zoom and orientation. See **Controlling the Map** for more details.
- Map Layers Selects which map layer will display. See **Controlling the Map** for more details.
- Active Layout Toggles between all saved layout tabs. See **Home Screen Layout Tabs** for more details.

Controlling the Map

The 20/20 displays high definition maps while operating. Different map layers may be selected and viewed during operation.

The map will default to displaying the tractor / implement in the center of the screen at a preset zoom level. Control buttons are located on the map to adjust settings.



- 1. Map Splitting:
- To split the map viewing area into two maps, press *Split* in the top right of the map. When viewing two maps simultaneously, any adjustments done to one map (other than adjusting the legend) are also applied to the other map. (e.g. zooming in on one map will also zoom in on the other map.)
- To exit the split map view, press *Full* on either map to change the view to only that map.
- 2. The **Red / White Arrow** indicates north. Change the map orientation by pressing the compass. There are three orientation modes:
- North Facing The top of the map is always pointed north. The tractor icon will change directions on the screen. This is the default orientation mode.
- Implement Facing The implement icon is always pointed towards the top of the screen and the map rotates around the implement.
- Custom place two fingers on the map and rotate it. This will lock the map into the selected orientation. Press the compass to return to north facing mode
- 3. Press the *Field* button show the entire field.
- 4. Press the *Tractor* button to keep the tractor / planter centered in the screen. Zoom level will be reset and centered on the tractor.

- 5. Press the *Perspective View* button to toggle the map view angle between 0, 65, and 75 degrees.
- 6. Custom **Zoom**:
- Press *Zoom in (+)* or *Zoom out (-)* to change zoom level. Alternatively, use a pinch-in or -out gesture with two fingers to change zoom level.
- 7. Press *Show* to toggle the map legend on, or *Hide* to toggle it off. The map legend will display differently for each map layer. Most legends may be edited.
- Press and hold on the legend and drag up / down to adjust the high or low ends of the legend.
- Tap on the legend to open a popup that allows for adjustment of high / low values and number of steps, or use the auto-adjust button to automatically add a set number of steps.
 Press *Enter* to return to the home screen.



General Mapping Principles

- All maps are generated at 5Hz except for SRI (2Hz), meaning there are 5 data points mapped for each second of time.
- Mapping is drawn on a row-by-row basis.
- A dark line will be mapped on either side of the implement to distinguish passes.
- Rows which are inactive or are not collecting information on a row will not map (e.g. a row

does not have load cell installed will not map down force).

- Active map layers may be changed at any time by selecting a different layer.
- Some map layers require specific Precision Planting products to be installed on the implement to generate the information necessary to create that layer.
- Some map layers will not be generated until application begins.
- If the map has moved away from the tractor / implement location, a white arrow will appear on the edge of the map pointing in the direction of the tractor / implement.

Swath Control Screen

The Swath Control screen allows the user to manually swath rows on / off, configure a swath control plan, record a boundary, or simulate headlands.



Swath Settings

Use these settings to determine how the 20|20 draws coverage, to change which parameters the 20|20 will use to swath on / off, or to enter an offset to use when recording boundaries.

The 20/20 will not swath off to any option under Swath Control Plan which is set to Disabled.

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Setting **Always Draw Coverage** to Enabled will cause the 20|20 to draw coverage whether the 28 of 138

Simulated Headlands



Select a width for Field (Exterior) or Inner to set the simulated headland width for either option.

() INFO

A Boundary file must be assigned to the field to enable simulated headlands.

Recording Boundaries



Use the following process to record a boundary using the 20|20.

- 1. Use the dropdown menu to select an existing boundary to rewrite, or create a new file name.
- 2. Press Record Field (Exterior) or Record Inner to begin recording either type of boundary.
- 3. Use *Pause* or *Cancel* to temporarily or permanently stop recording the current boundary. Use *Resume* to unpause.
- 4. Use *Change Direction* to correct the tractor heading, if necessary.
- 5. Press *Save* to keep the current recording.

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To ensure maximum accuracy around outer field corners, press *Pause* after reaching an outer corner. Complete the turn, then back fully into the corner. Press *Resume* when the tractor is properly repositioned.

Status Center

The Status Center is displayed in the top right and contains at-a-glance information about Speed, GPS, Internet connectivity, and system alerts.



The satellite icon indicates that GPS is being used as the speed source. If an icon of a tractor and radar pulse is shown, the speed source being used is radar. the $\langle R \rangle$ icon indicates that the tractor is moving in reverse.

Internet connection status is displayed below time of day. A Wi-Fi symbol indicates wireless Internet connection, while a $\langle \dots \rangle$ icon indicates hardwired internet connection. A small rectangular icon will be displayed when paired with a Panorama operation.

Press the Status Center to open a popup with more detailed information.



Press any of the events to open a detailed description of that event. Press GPS to navigate to the GPS section of the Diagnose screen. See **GPS** in the **Diagnose** section of this guide for more details.

Setup

Press *Setup* to open the **Navigation Menu**. The Navigation Menu displays a screen with basic implement information and allows the user to navigate to the different sub-menus of the 20|20. The system pathway displayed in the top right will help the user to orient themselves while navigating the 20|20.



Navigation Menu Overview

- 1. **Fields**: Change the active field, assign prescriptions/boundaries, create or edit Client, Farm, & Fields, change crop, and share data using Passmaster.
- 2. Products: Set up / assign crop hybrids and tank mixes.
- 3. **Equipment**: Configure the implement and tractor measurements, set up Ethernet devices and CAN buses, view / change GPS, Radar, and Quick Start settings, and save or load Equipment profiles.
- 4. Systems: Configure all Precision Planting products installed on the implement.
- 5. **Diagnose**: Access diagnostic information related to the display and all products being controlled / monitored on the implement.
- 6. Calibrations: Run all calibrations for the implement, tractor and other systems.
- 7. **Settings**: Import / export / delete data, perform software updates, connect to the Internet / Panorama, and change user preferences associated with the monitor.

Alerts are accessible for each system on the specific system screen. See **Alerts** in the **Systems** section of this guide for more details

Using the Navigation Menu

2025.1.x software utilizes a nested navigation theme. Press on any of the sub-menus displayed in the Navigation Menu to jump to the **Landing Screen** for that sub-menu. The sub-menu will then expand in the Navigation Menu, displaying additional sub-menus for the previous selection. Instead of using a Back button, instead press any option in the Navigation Menu to return to that page.



() INFO

Several sub-menus allow the user to add different types of hardware to an Equipment profile or System. Whenever a hardware device is added, that hardware will appear in the Navigation Menu under the Equipment or System that it was added to.

A ► Setup ► Systems ► Seeding ► Hardware	0.0 mph 1:13 pm 2 mm 0 ↔
	Implement
	Seeding -
	Hardware 👻
	 SRM Seed Sensor Vacuum Sensor vDrive Primary
	Nitrogen →
Add Seeding Hardware 🕀	A Home

Press on the desired hardware device in the Navigation Menu to quickly access **Install Settings** for that device. See **Hardware** in the **Systems** section for more information on Install Settings and **Operation Settings**.

Several types of icons exist which indicate actions that may be performed by the user as they navigate the different screens of the 20|20

Three vertical dots may be pressed to access a **Secondary Menu** for the item on which they appear. The Secondary Menu allows the user to perform certain actions, such as updating / loading an Equipment profile or deleting a misconfigured hardware device.

A ► Setup ► Systems	_		_)	5.4 mph & IIIII	11:16 pm ∳ ↔>
Seeding > Default Rate 30,000 seeds Delete	te 🔟					
	Oefault Rate 2.00 in					

Arrows, also known as Chevrons, indicate that an item may be pressed to navigate to a different screen, rather than using the Navigation Menu.

Tractor			
Fields

↑ Setup + Fields		ک	mph	! «··»
Client Test	▼ Farm Test	· ·	Fields	•
♂ Active Field > Test Test			Active Field	Þ
FIELDS			😵 Products	
♂ Test > Client Test			😽 Equipment	
Farm Test			👫 Systems	
			🔀 Diagnose	
			Calibrations	
			🔅 Settings	
	Add Field 🕀		🟫 Home)

The Fields menu is used to:

- Create and edit Clients, Farms, and Fields
- Set the active crop for each field.
- Select the season start year.
- Assign imported boundaries and prescriptions.
- Change the Active Pass to replant or make multiple sprayer passes.
- Change some critical **Operation Settings**, such as seeds / disk.
- Share data with other 20|20 monitors using Passmaster.

Precision Planting uses a three-tiered naming structure for field names: Client > Farm > Field. Each tier of the naming structure becomes more specific. A table of all fields is displayed on the **Fields Landing Screen**. This table may be filtered by Client and Farm using the dropdown boxes at the top. At all times there will be an active field, designated by a blue-green outline. The active field is the field in which all data and mapping is currently being created for and stored under.

Press Add New Client / Farm from either of the dropdown boxes to add a new Client or Farm.

Press Add Field + at the bottom to add a new field to the selected Client / Farm.

Press the three dots next to any field name to delete Client, Farm, or Field.

(i) NOTE

The active Client / Farm / Field may not be deleted.

⊙ тір

To delete a misspelled Client or Farm, a Farm and / or Field must be created under the misspelled entry for the delete option to be available.

Pressing on any field in the table will jump to the Field Setup screen.

Field Setup

↑ Setup > Fields > Field Setup				5.4 mph & IIII	11:02 pm
Test Inactive					
Field Details	Prescri	ptions	Systen	n Settings	
Details					
Client	Test				
Farm	Test				
Field Name	Test		•		
Boundary File	None	Make a selection from the menu on the le			o edit
			e.		
Done ⊘			Make Field Active	đ	

Use the tabs at the top to navigate to the different areas of Field Setup.

Field Details

↑ Setup > Fields > Field Setup				5.4 mph & IIII	11:02 pm ∳ ↔>		
Test Ø Active							
Field Details	Prescri	otions	Syste	m Settings			
Details							
Client	Test						
Farm	Test						
Field Name	Test	Make a selection from the menu on the left to					
Boundary File	None						
Season		your settings here.					
Сгор	Corn						
	2025						
Done ⊘			Field Activated	ず			

Use this tab to:

- Make a field active using the button at the bottom. If the field is already active, this button will read *Field Activated*. Press *Done* instead to exit field setup without making the field active.
- Change the Client / Farm that the field is assigned to.
- Change field name.
- Assign a boundary file.

Boundary assignments are saved to the Equipment profile. When switching Implement types (e.g. from planter to sprayer), it will be necessary to reassign boundaries on field setup.

• Change field Crop setting.

Changing Crop setting in the Field Details tab **does not** change seeds/disk for vDrive. It is necessary to use the **System Settings** tab to also change seeds/disk every time the Crop setting is changed.

- Change crop year setting.
- Change the active pass to ignore existing coverage when replanting or making multiple sprayer passes.

↑ Setup > Fields > Field Setup			mph 😵 ⅢⅢ 🛛 💠 «··
Test Ø Active			
Field Details	Prescr	iptions	System Settings
Prescriptions		Section 1	
Seeding		None	pop_orange
Seeding Prescription	rd_vss_demo	non blue	
Section 1	pop_orange	pop_side	
Section 2	() None		
Depth			
Depth Prescription	None		
Contine 1			
Done ⊘		Field A	ctivated 🧭

Prescriptions

Use this tab to select and assign the desired prescription file and to assign an attribute of that file to the desired control (or rate) section. See the above image for a depiction of correctly assigning a prescription attribute to a control section.

Different systems, e.g. Granular, Seeding, etc. will appear in this window only after those systems have been configured.

(I) INFO

Prescription assignments are saved to the Equipment profile and Year. When either is changed, it will be necessary to reassign prescriptions.

(i) NOTE

Prescriptions are not imported into the display on this screen. Navigate to **Setup > Systems > Import** to import all types of data into the 20|20.

💭 ТІР

The **Edit Prescription** screen is not available from the fields screen. To access the Edit Prescription screen, open the appropriate **Control Screen** once a prescription has been assigned and select *Edit Prescription* on the right. See **Control Screens** in the **Home Screen** section of this guide for more details.

System Settings

↑ Setup > Fields > Field Setup)			5.4 ^{mph} 양 IIII	11:03 pm 🔶 ↔	
Test C Active						
Field Details	Presci	riptions	Syste	m Settings		
System Settings						
Seeding						
Default Population	30,000 seeds/ac					
Default Tank	Orange	'	•			
vDrive Primary		Make a selection from the menu on the lef				
Seeds / Disk 27 vS	et Corn vSet Specialty	your settings here.				
Insecticide						
Defeult Dete	0.0 lbs/co					
Done ⊘			Field Activated	Ì		

Use this tab to change **Operation Settings** for different system hardware devices, such as seeds/ disk. Changes made here will apply to all hardware devices across all rows.

Active Field

↑ Setup > Fields > Active	Field		\mathbf{b}	5.4 mph & IIII	11:03 pm
Test C Active				🖶 Setup	
Field Details	Prescription	s System Settings		ॡ Fields	
Details				Active Field	-
Client	Test			Passmaster	
Farm	Test			Field Summ	arv ▶
Field Name	Test				
Boundary File	None			😵 Products	
Season		Make a selection from the menu on the left to edit your settings here.		😽 Equipment	
Сгор	Corn			👫 Systems	
Year	2025			•	
Active Pass 🔹	1			🔒 Hoi	ne

Press the active field on the **Fields Landing Screen**, or press *Active Field* under **Fields** in the Navigation Menu to navigate to the **Active Field** screen. Use this screen to access all options from the **Field Setup** screen with the Navigation Menu still visible.

Passmaster



Press *Passmaster* under **Active Field** in the Navigation Menu to share field maps between multiple 20|20 monitors that are paired with the same Panorama operation. This is referred to as **"Subscribing"** to a pass. Data sharing is not limited to Coverage - all data will be shared. Data sharing is field-specific, the user must select what passes to share for each field on each DBM.

A table of all passes is displayed on this screen. Press any pass to begin subscribing to it. Any pass that is subscribed to is indicated by a blue-green outline. Press the three dots on a subscribed pass and press *Disconnect* to stop subscribing to it.

(i) NOTE

"Pass / Passes" above refers to the entire field coverage map for a specific DBM in the listed field, not a single down-and-back field pass.

This table may be filtered by DBM Name, Client, Farm or State using the filters at the top.

(i) NOTE

DBM Name will default to the serial number of the DBM. This name may be changed by accessing the DBM on Panorama.ag and changing the nickname.

() INFO

"State" filters the table by passes that are currently subscribed to (active) or unsubscribed to (inactive).

Subscription is not limited by field name or Implement type. Any pass may be subscribed to. However, map layers on the home screen will only build for systems that are installed and configured on each implement / 20|20. Coverage will always build.

🗘 ТІР

Passes from a DBM are not available by default to share "with itself" using Passmaster. In any case where this would be desirable, it is possible to export the field map data from the 20/20 onto a USB drive, and then re-import that field map data into the 20/20. The pass will then be available to subscribe to on the Passmaster screen.

() IMPORTANT

The speed of data sharing will be limited by Internet connection quality for all sharing 20|20 monitors. With high-quality Internet connections, data sharing can appear to be live. Lower quality connections will have increased delay. Precision Planting recommends 1mb upload / 1mb download speed per DBM.

Field Summary



Use this screen to view various field-related metrics for the active field. General information, such as hours, acre counters and seed count is shown after navigating to **Field Summary**.

Press any of the options under Field Summary the Navigation Menu to view detailed information regarding hybrids, tank mixes, or systems. Use the tabs at the top to switch between the current pass summary and the entire field summary.

(i) NOTE

"Pass" in this context refers to the current field coverage map and its map layers, not a single down-and-back pass.

Products



The **Products** menu is used to set up all hybrids and granular / liquid tank mixes. A list of seeding, liquid, and granular systems showing basic hybrid / tank mix information and indicating active rows for the hybrid / tank mix is shown on the **Products Landing Screen**.

Hybrids



Press [**Seeding System Name**] under **Products** to add, delete or modify hybrids. A table of hybrid entries is displayed in the center. Press *Add Hybrid +* to immediately add a numbered hybrid entry to this table. Press the three dots next to any entry displayed in the table to delete it.

Press on any entry once it has been added to open Hybrid Setup.

Hybrid Setup

Use the Hybrid Setup screen to select or enter a hybrid name, modify hybrid volumetric attributes, or set the active rows for the selected hybrid.

The **Hybrid Name** list is limited to 10 names. Adding an eleventh name will remove the oldest name.

♠ Setup > Products > Seeding > Hybrid 2			mph 😮 IIIII 🔶 <>
Hybrid Setup: Hybrid 2	Dicht	Hybrid Name Select the hybrid from the list o	r add a new one
Hybrid Name	102SLS	None	1412
Seeds Per Unit	80000	32Z18	2750HQ/ND
Seeds Per Pound	0	1553RR	1220Bt
Pounds Per Unit	0	1042	25T07 RR
		4300RR	102SLS
		21637	
Add Treatment 🕂		Add From Database +	Add Custom 🛨
Cancel 😣		Save and	d Finish 🥥

Precision Planting Product Support recommends using the table of hybrid entries displayed on **Setup > Products > [Seeding System Name]** as the "master list" of hybrids, rather than the **Hybrid Name** list on the Hybrid Setup screen. Select a hybrid entry and modify the active rows to "change" hybrids. Adding / deleting hybrids from the list on the Hybrid Setup screen will not remove saved names for the entries. The list of hybrid entries is saved to the Equipment profile.

Tank Mixes



Press any of the liquid or granular systems under **Products** to add, delete, or modify tank mixes. A table of all tank mixes for the selected system is displayed in the center. Press *Add Tank Mix +* and enter the desired name for the tank mix. A new tank mix will then be displayed in the table.

Press on any tank mix in the table to set active rows for that mix and add granular or liquid products to it.

↑ Setup > Products > Nitrogen > Test 1			mph	12:31 am 🔶 ↔
Tank Mix Setup: Test 1		Water		
Active Rows	None	Delete Product	Edit Product	
Target Rate	6.00 gal/ac			
Carrier				
Product	Water			
Amount	5.00 gal/ac			
Product 1				
Product	UAN			
Add Product 🕂				
Cancel 😣		Save	and Finish 🥥	

💭 ТІР

If setting up a liquid tank mix with a carrier, the carrier must be added first. Changing **Target Rate** on this screen will increase only the amount of carrier. See the above image for an example. The system will continue to apply the rate commended in the Control Screen, regardless of tank mix ratio.

() IMPORTANT

The 20|20 will not indicate on the map when a new product is added to an existing tank mix. To track changes to a mix on the map, set up a new mix instead of editing an existing mix.

Equipment



The **Equipment** menu is used to configure, save, and load different Cab or Implement profiles. Use this menu to enter all Cab / Implement specifications and measurements, to configure GPS and Radar location and settings, and to set up Ethernet / CAN.

Press *Switch Implement Type* at the bottom to select the desired Cab / Cart / Implement combination.

Switching Implement will erase any unsaved changes to the active Cab / Implement profiles. Ensure to save all changes before switching Implement.

() INFO

A new 20/20 will display only a tractor cab on the Equipment Landing Page on first boot up. Press *Switch Implement* to select and configure the desired equipment combination. This will also occur if the user performs a **Delete All Data**.

Quick Start Settings



Use the tab at the top of the **Equipment Landing Screen** to select **Settings** for the Quick Start function. The Quick Start **Control Widget** will use the values from this screen when it is enabled. Quick Start allows the user to begin applying product at the simulated **Quick Start Speed** after the **Quick Start Delay** countdown. It will continue to run until either the **Quick Start Timeout** is reached, or until the 20|20 registers speed from the **Primary Speed Source**.

() INFO

Kinematic Model and Primary Speed Source are not typically changed from their default settings (Multibody and GPS). Change these settings only when advised by Precision Planting Product Support.

Cab / Implement Setup



Select the Cab or Implement under the Equipment tab to begin setup.

Use the left window to select the desired parameter and the right to window to make changes to that parameter.

Select **Advanced** for **Frame / Boom Type** if utilizing the **Advanced** table to adjust individual row / nozzle positions. See **Advanced** later in this section for more details.

() INFO

Row Spacing / **Nozzle Spacing** refers to the physical spacing between rows on the Implement. **Controlled Spacing** refers to the spacing between each of the current **Active Rows**. The 20|20 will use Controlled Row Spacing to determine population / rate.

🖓 ТІР

It is not necessary to assign a value to **Tanks** unless a SRM for a Rate Control Module will be installed on the physical tank.

() IMPORTANT

Ensure to set PDM to Not Present for systems fusion the single or triple CAN sensing harness.

Hardware

♠ Setup > Equipment > Tractor	or ▶ Hardware		(·D	0.0 mph	2:12 pm ♦ ♦••
GPS > Modules 1	●》 Radar > Modules 1	:			Products	
					🖧 Equipment	
					Tractor	•
					Hardware	•
					GPS	
					Radar	
					Modules	
					Measuremer	nts 🕨
	Add Hardware +				숚 Hom	ne

Use the **Hardware** screen to configure GPS receiver or Radar location by pressing *Add Hardware +* at the bottom and following the setup wizard. Press the three dots on any hardware device in the center of the Hardware screen to run the setup wizard again with **Edit Locations** or to delete it.

All settings from the final step of the wizard may be accessed again by selecting the desired device under **Hardware** in the Navigation Menu.



(i) NOTE

GPS location will default to the Cab. Adding GPS to the Implement hardware screen will remove it from the tractor, and vice versa. Configure GPS on the Implement only if the 20|20 is connected to a GPS receiver that is mounted on the Implement. Radar may not be added to the Implement.

Modules

↑ Setup > Equipment > Tractor > Modules		\rangle	5.4 mph 11:0	9 pm ∢••>
P TRACTOR ETHERNET MODULES	F TRACTOR CAN BUS MODULES		😵 Producte	
No Ethernet Modules have been configured for the Tractor.	CAN Bus Modules can't be added to the Tractor.		🔂 Equipment	
			Tractor	•
			Hardware	
			Modules	
			Measurements	
			Save / Load	
4 Unconfigured Ethernet Modules			Planter	
Configure Tractor 🕼				
			🚸 Svstems	Þ
Configured System Schematic 🔚			🔒 Home	

↑ Setup > Equipment > Planter > Modules		\rangle	5.4 mph & IIII	11:09 pm 🔶 ↔
PLANTER ETHERNET MODULES	야응 PLANTER CAN BUS MODULES		Tractor	
No Ethernet Modules have been configured for the Planter system.	No CAN Bus Modules have been configured for the Planter system.		Planter	•
			Hardware	
			Modules	
			Measureme	ents →
			Advanced	
	😥 7 Unconfigured CAN Bus Modules		Save / Loac	1
Configure Planter 🖗	Configure Planter ≁€		👫 Systems	
Configured System Schematic 🔁				me

Use the **Modules** screen to set up Ethernet layout and serial numbers, and CAN module sequence and location.

If the 20|20 is connected to Ethernet or CAN modules and all modules / harnesses are undamaged, then all detected but unconfigured modules will be shown under the left and right windows in the center as pictured above.

(i) NOTE

CAN modules are only available for configuration on the Implement. Only Ethernet modules may be set up on the Cab.

Press *Configure (Implement name / Cab name)* in either window to begin setting up Ethernet or CAN modules.

Ethernet Modules

↑ Setup + Equipment + Tractor + Modules + Ethernet	2.8 mph 11:09 pm [™] IIIII • • • • •	
Add Detected Modules		STEP 1
Configured Modules	Unconfigured Module	Serial Number
No ethernet modules have been configured. Select the unconfigured modules that you want to add or continue to the	10" Display	40108647
next step to edit modules manually.	FieldView Module	60213699
	Ethernet Switch	102000089
	16" Display	70100019
	Add All Modules 🕕	Add Selected Modules 🚔
Cancel 😣	Contir	nue >

If all Ethernet modules are detected correctly in the left window, press *Add All Modules +* in the bottom of the right window on **Step 1** to confirm and save auto-detected modules. To add only select modules, press each desired module in the left window, then press *Add Selected Modules* to confirm and save each highlighted module.

↑ Setup ► Equipment ► Tra	4.4 ^{mph} ℰ∭	11:09 pm •••						
Add Modules Manually			STEP :	2 • • •				
Module	Serial Number							
10" Display	40108647							
FieldView Module	60213699							
Ethernet Switch	h 102000089							
16" Display	70100019							
		Would you like to add any mod	lules manually	?				
Delete Last	Delete All 🔟	Add Modules 🤆	9					
<	Back	Continue >						

(Optional)

If Ethernet modules will be connected later, modules may be set up manually on **Step 2** if desired. When using manual setup, it will be necessary to know the serial number of the manually added modules for the next step. Press *Add Modules +* in the right window and select the correct module from the popup.

↑ Setup > Equipment > Tra	5.3 mpt	n 11:09 pm 🔶 ↔			
Configure Module Seria	l Number			s	TEP 3 •••
Module	Serial Number	Module Serial I	Number		
10" Display	40108647		40100	647	
FieldView Module	60213699		40100	0047	
Ethernet Switch	102000089	7	8	9	
16" Display	70100019				$\langle \times$
		4	5	6	
		1	2	3	
		0	00	000	·
Enter ⊘					
<		Save and Fi	nish ⊘		

Confirm or enter correct serial number for each device on **Step 3**. Press *Save and Finish* to exit setup and return to Modules. Ensure that Ethernet devices are listed correctly below DBM in the left window.



🗘 тір

Ethernet modules may also be added to the implement. This is intended for Ethernet switches and Vision cameras. Configure displays on the Cab to ensure correct function.

CAN Modules



If all CAN modules are detected in the correct sequence in the left window, press *Add All Modules +* in the bottom of the right window on **Step 1** to confirm and save auto-detected modules. Use the tabs at the top to repeat this process for each CAN bus.

() INFO

It is possible to add only some detected CAN modules by pressing each desired module in the left window and then pressing *Add Selected Modules*. This is typically not necessary in CAN Module setup if all modules are detected correctly.

ト Setup ▶ Equipment ▶ Planter ▶ Modules ▶ CAN Bus Modules						11:10 pm	
Add Modu	ules Manually				STEP	2 • • •	
	CAN A		CAN B		CAN C		
Number	CAN Bus Module						
1	SRM						
2	SRM						
3	SRM						
4	SRM						
				Would you like to add any	modules manually	?	
Dele	ete Last 📕	Delete All 🔟		Add Modul	es 🕀		
< Back				Continue	• >		

(Optional)

If CAN modules will be connected later, modules may be set up manually on **Step 2**. Press *Add Modules +* in the right window and select the correct module from the popup, then select the correct number of modules in sequence. Repeat until all modules are added. Then use the tabs at the top to repeat this process for each CAN bus.

() IMPORTANT

Modules must be added in the correct sequence. For example, if a 12 row sensing system on a planter is using an SRM on each row, and a Smart Connector installed between rows 6 and 7, the user must add:

6xSRM > 1xSmart Connector (SC) > 6xSRM.

Û LIÞ

The FCIM is a Fendt Momentum-specific module. It will always be added after the first (PDM) SRM on CAN A.

☆ ▶ Setup	Setup > Equipment > Planter > Modules > CAN Bus Modules						
Assign Lo	ocations			STEP 3			
	CAN A		CAN B	CAN C			
Number	CAN Bus Module	Location	Assign Module Location				
1	SRM	None	PDM	Rows			
2	SRM	None					
3	SRM	None		PDM			
4	SRM	None					
	Clear All Locati	ons 🛞	Auto-Assign All 🚆	Clear Location 🛞			
K Back			Save	and Finish 🧭			

For standard planter configurations, press *Auto-Assign All* in the left window to automatically assign the correct location to each CAN module in sequence, starting with PDM (if set to present) or Row 1 (if PDM is set to not present). Then use the tabs at the top to repeat this process for each CAN bus.

() INFO

When configuring a sprayer boom, CAN B will auto-assign from right to left.

Alternatively, select the correct location for each module using the table in the left window. Use the tabs at the top of the table to toggle between types of location. Making a selection will automatically jump to the next module in sequence. Press *Clear Location* in the left window to erase the location for the module selected in the right window. Press *Clear All Locations* in the right window to erase all locations for the current CAN bus.

Configuration Review

Press Save and Finish after confirming correct module sequence / location to return to Modules.

🗘 тір

Daisy chain breaks and damaged harnessing will cause the auto-detect feature to function 62 of 138 improperly. Review the summary listed under **Implement CAN Bus Modules** to ensure the correct number of Bus devices were detected / added.

↑ Setup > Equipment > Planter > Modules	\triangleright	5.4 mph 11:13 pm ⓒ IIIII ↔ ↔	
PLANTER ETHERNET MODULES	F PLANTER CAN BUS MODULES		☆ Products →
No Ethernet Modules have been configured for the Planter system.	ParentDBMCAN ASRM 4CAN BSRM 3		Carlot Constraint
Configure Planter 😱	Configure Planter ≁€		Measurements
Configured Syste		🔒 Home	

Press *Configured System Schematic* at the bottom to view a schematic of the configured CAN bus(es)

Measurements



Use the Measurements screen to enter all Cab / Implement measurements.

The **Measurements Landing Screen** displays a QR code which will open a form-fillable, printable .pdf worksheet to assist with recording measurements, and a **Frame Layout** for the Implement.

Edit Measurements



Select the desired dimension in the left window and use the right window to modify the dimension. Some dimensions will expand in the left window when pressed to display a graphic indicating what to measure. Continue scrolling after entering a value to view all available dimensions.

💭 ТІР

Some dimensions have a **Measure to Left / Right** toggle in the right window. A value must be entered and saved using the keypad before the toggle will function.



💭 ТІР

When configuring an Implement with multiple seed / application exits, set all rows for each exit to **None** before selecting the rows for any exit.

↑ Setup + Equipment + Planter + Measu	5.4 mph 11:14 pm È ₩₩ ♦ ↔>	
Planter Measurements	Rows	Tractor
Wheel Distance 17	in All Odd	Planter -
Exit 1	Even Left	Hardware
Exit 1 16	Right None	Modules
Exit 2		Measurements -
Rows		Edit Measurements
Exit 2 0.	in	Advanced
		Save / Load
	Custom	Home

Advanced



Implements will display the **Advanced** option in the Navigation Menu when **Advanced Frame Type** is selected on the implement profile. The Advanced screen allows the user to set the Row Unit type (planter only) for each row individually. Use this feature on mixed-row unit planters to ensure correct system operation. Ensure to select **Advanced** for **Frame Type / Boom Type** if utulizing the **Advanced** table.

() IMPORTANT

It will be necessary to also select the correct load cell for each row unit if running DeltaForce or AirForce on all mixed-row unit planters.

This screen also allows the user to enter custom **Application Point** (front-to-back) and **Lateral** (side-to-side) offsets for each row or nozzle.

💭 ТІР

To streamline setup when using the **Advanced** table, first navigate to **Setup > Equipment >** [Implement Profile] and select the Frame / Boom Type that most closely resembles the physical implement. Proceed to **Edit Measurements** and assign rows / nozzles to the different exit points. Then return to the Implement profile and switch the Frame / Boom Type to **Advanced**. This will give each row / nozzle a default value in the Advanced table, rather

Save / Load

↑ Setup > Equipment > Planter > Save / Load		5.4 mph & IIII	11:15 pm 🔶 ↔
♂ Test Status Active	:	Tractor	
Type John Deere Center Trailing 15.0 ft 6 Rows Last Modified February 26, 2025 7:30 PM		Planter	•
		Hardware	
		Modules	
		Measurem	ents 🔹 🕨
		Advanced	
		Save / Load	d
		Systems	
Save Current Planter Configuration 😍		n Ho	ome

Use the **Save / Load** screen to save, update, and quickly switch between different Implement profiles. A table of all saved profiles of the current type are displayed in the center. Press *Save Current (Equipment Name) Configuration* at the bottom to save the current Product / Equipment / System / Home Screen configurations with the desired name.

Press the three dots on any profile in the table to Load, Update, or Delete the profile. Update saves any current changes to the selected profile.

Systems

The **Systems** menu is used to configure all Precision Planting control and sensing hardware, **System Alerts**, swath settings and control sections. The user may also use the Systems menu to adjust **Operation Settings** for hardware, such as disabling failed sensors and enabling overrides.

†)	Setup • Sys	tems						\mathbf{b}	5.4 mph & IIII	11:15 pm 🔶 ↔
	Implement > PDM	1 0 0	2 • •	3 0	4	5	6		Nitrogen Closing Down Force	
	o Iardware SmartFirmer Ride Quality Frame-Moun Switch Range Input	6 Sensor 6 ted Lift 1 Work State 1	Swath S Rows Me Center Po	ettings rged 0 osition 0%		Cab Control Left 1-2 Middle 3-4 Right 5-6	Module		Insecticide Depth Row Cleaner	
	Sensor Gyro 1 Seeding >	: ••••••••••••••••••••••••••••••••••••	Closi	ng >	:	Down F	orce >	:	 Diagnose Calibrations 	
			Add Imp	element Syste	m (+)				🟫 Hom	e

There will be a default system which is either named after the type of Implement profile selected in **Equipment**, or simply titled **Implement**. This system is where all implement-wide hardware, such as lift switches and SmartFirmers, will be configured. All other systems must be added by pressing *Add Implement System* at the bottom of the **Systems Landing Screen**.

The System Landing screen also displays an overview of default system hardware, a summary of swath and CCM settings, and a list of all control and sensing systems which have been configured.

This guide will detail general system information and basic setup. Refer to all applicable operator's guides for system-specific configuration, parameters, and settings.

(i) NOTE

If **Air Seeder with Fertilizer and Seeding Ranks** is the selected Implement, there will be two default systems named **Seeding Ranks** and **Fertilizer Ranks**. Each control / sensing system must be added under the appropriate set of ranks by pressing either *Add Seeding Ranks System* or *Add Fertilizer Ranks System* at the bottom.



Adding / Deleting a System

Pressing *Add Implement System* will open a popup that allows the user to select the **Type** of system.



Selecting the type of system opens a second popup which allows the user to select a preset **Name** or enter a custom **Name**. It is advised to add all systems before proceeding to **Hardware Setup**.

A ► Setup ► Systems	5.4 mph 11:17 pm			
				Systems -
Liquid				Cancel 🛞
Nitrogen	Fungicide	Insecticide		Starter
Herbicide	Spray	Рорир		Custom
Nitrogen > E Default Rate 10.0 gal/ac	Depth > Default Rate 2.00 in	Row Cleaner > Default Rate 0.0 psi	I	Insecticide
Press the three dots next to any system in the center to delete it.

↑ Setup > Systems				\mathbf{b}	5.4 mph & IIII	11:16 pm 👎 👐
Hardware	Swath Settings Rows Merged 0		Cab Control Module		🖨 Setup	
Ride Quality Sensor 6 Frame-Mounted Lift 1	Center Position 0%		Middle 3-4 Right 5-6		🐙 Fields	
 Switch Range Input Work State Sensor 					😵 Products	
Gyro 1					😽 Equipment	t ⊧
Seeding >	Closing >	:	Down Force >	:	🕂 Systems	•
Default Rate 30,000 seeds/ac	Default Rate 35.0 lbs		Default Rate 100 lbs		Implement	
Nitrogen > Default Rate 10.0 gal/ac	⑦ Depth > Default Rate 2.00 in	:	Row Cleaner > Default Rate 0.0 psi	:	Seeding	
☆ Insecticide > Default Rate 0.0 lbs/ac					Nitrogen	
					Closing 👻	•
Add Implement System 🕀					n Ho	me

Once all systems have been added, select a system in the Navigation Menu or press a system name in the center to navigate to that system screen.

() IMPORTANT

All system **Names** are placeholders only and do not determine available hardware. Available hardware is determined by system **Type**. Ensure to configure all appropriate hardware in the desired system. Do not configure multiple system's hardware in one system. Doing so will cause all hardware devices to malfunction.

Implement (Default) System Settings



Use the left window on the Implement (Default) system screen to view system settings.

Swath Settings

Press *Merged Rows* in the right window, then press *Edit Swath Settings* in the right window to tie end rows together using a setup wizard. Select the number of rows to merge on Step 1.

↑ Setup > Systems > Implement > Swath Settings	mph 1:36 am
Edit merged rows	STEP 1
	Merged Rows Select the number of rows you would like to merge on both ends of the implement. Merged rows will swath on and off together as a unit.
	2 Rows
	3 Rows
	4 Rows
< Back	Continue >

Step 2 (optional) allows the user to enter a positive or negative value to change the point that the 20|20 will use as the center of the merged section. Review choices on Step 3, then press *Save and Finish*.

CCM Settings

The 20|20 will assign approximately 33% of the implement rows to each switch on the CCM. Press *Cab Control Module Mode* in the left window and select *Custom* in the right window to manually assign rows to each CCM swath switch. Select each switch in the left window, then select a preset option in the right window, or press *Custom* in the bottom right window to assign custom rows to each switch.

Setup > Systems > Implement						11:18 pm
Settings 😳		Corn Ale	erts 🚸		A Equipment	
Implement Settings		Left Switch			👫 Systems	
Swath Settings		All	Odd		Implement	•
Merged Rows Row Sensitivity	0 0%	Even	Left		Hardware	Þ
Cab Control Module		Right	None		Seeding	
Cab Control Module Mode Cus	tom				Nitrogen	
Left Switch 1,	3, 5				Closing	
Middle Switch N	lone				Down Force	
Right Switch N	lone					
		Cus	tom		Hor	ne

Other Systems

♠ ► Setup ► Systems ► S	eeding		\triangleright	5.4 mph 论 IIII	11:19 pm ♦ ♦•
Settings	¢	Corn Alerts 🚸		A Equipment	
Seeding Settings				👫 Systems	
Control Sections				Implement	
Section 1	Even			Seeding	.
Section 2	Odd			Hardware	Þ
Section 3	None				
Section 4	None	Make a selection from the menu on		Nitrogen	
Coverage Settings		the left to edit your settings here.		Closing	
Start Offset	0.00 in sooner			Down Force	
Stop Offset	0.00 in sooner			Incontinida	•
Coverage Gap 🔹	No Gap			🔒 Hor	ne

Other systems will have different settings available in the left window depending on system Type.

Each of these settings are system specific. Typical settings are detailed here.

Control Sections

Used to set up different rate sections. The rates for each control section are adjustable individually or collectively using the system **Control widget** on the home screen.

Start / Stop Offsets

Used to fine-tune swath timing by commanding the selected system to start or stop applying sooner or later.

Coverage Gap

Used to determine the gap between the swath on / off point and previous coverage. This will be affected by any Start / Stop Offsets.

Module Row Sensitivity

Used to determine when a module which applies product across multiple rows (e.g. vApply Base) will swath on / off.

CCM Autoload

Used to enable / disable autoloading for the system. Any system with this setting enabled will dispense product when the left and right swath switches on the CCM are clicked up.

Coverage Method

Used to determine when the 20/20 will build Coverage. Any system set to **Work State and Applying** will not map Coverage unless the lift switch reads lowered. Population and other application maps will still build.

Active Rows

Sets the active rows for the system. System hardware on any rows not set to active will be deactivated.

Default Population / Rate

Sets the out-of-prescription and autoload rates for the selected system.

Operation Settings



Other critical hardware settings will be available once system hardware has been configured. See the following section of this guide for more information on **Operation Settings**.

Hardware Setup



Press *Hardware* below each system in the Navigation Menu to set up that system's hardware. Press *Add (System Name) Hardware* at the bottom to open a popup which allows the user to select the desired hardware device.



Selecting a device will automatically open the setup wizard for that device. Some hardware setup wizards will have more steps than others.

A list of all configured hardware devices will be displayed in the center of the screen.



Press the three dots next to any hardware device to delete it or **Edit Locations**, which will run through the setup wizard again.

Hardware Settings

Hardware settings are divided into **Install Settings**, which are typically adjusted during initial setup, and **Operation Settings** which may be adjusted multiple times per season / year.

Install Settings are accessible on the final step of each hardware setup wizard, and on the specific system hardware screen after that hardware device is added.

Configure	e vDrive Primary	v Settings		STEP 4
Location	CAN Connection	Rows	Edit settings for module	on Row 1, CAN Black
Row 1	Black	1	Swath Output Mode	Off While Planting
Row 2	Black	2		
Row 3	Black	3	Seeds / Disk	27 vSet Corn vSet Specialty
Row 4	Black	4		
Row 5	Black	5		
Row 6	Black	6		
Row 7	Black	7		
Row 8	Black	8		
Row 9	Black	9		
Custo	om Select 🚔	Select All Rows 🗹		
< Back		Save	and Finish 🥥	

↑ Setup > Systems > Seeding > Hardware > vDrive Primary

-- mph

n rh → Setup)	Systems ► Seed	ing ► Hardware ►	Drive Primary	/	\triangleright	5.1 mph 😵 IIIII	11:22 pm
Location	CAN	Rows	Edit settings for r	nodule on Row 1, CAN Bla	ick	Seeding 🔺	•
Row 1	Black	1	Swath Output Mo	de Off While Plant	ing	Hardware	
Row 2	Black	2	Seeds / Disk	27 vSet Corn vSet Specia	alty	SRM S Sensor	eed
Row 3	Black	3				🚊 mSet	
Row 4	Black	4					
Row 5	Black	5				🧐 Flow R	educer
Row 6	Black	6				Flow R Motor	educer
						🕒 Vacuur	n Sensor
						VDrive	Primary
						Nitrogen 💌	•
Custom	Select 🚔 Sele	ect All Rows 🗹				숚 Hon	ne

Operation Settings are accessible from the left window of the specific system screen after the hardware device is added. It may be necessary to scroll to view all Operation Settings.



Some Operation Settings (e.g. vDrive seeds / disk) are also available under the **System Settings** tab on the **Field Setup** screen.

↑ Setup > Fields > Fie	ld Setup			5.4 mph & IIII	11:03 pm 🔶 🐝			
Test C Active								
Field Details	Presci	riptions	Syste	m Settings				
System Settings								
Seeding								
Default Population	30,000 seeds/ac							
Default Tank	Orange							
vDrive Primary		Make a selecti	on from the menu	u on the left to	edit			
Seeds / Disk	27 vSet Corn vSet Specialty		your settings here.					
Insecticide								
Default Data								
	Done ⊘		Field Activated	Ī				

🖓 тір

- Any device which doubles as a CAN Module (e.g. Smart Connector, BXM, vApplyHD Flex, NCM, etc.) must have the same location assigned to it during both Module and Hardware setup.
- Access all **Install Settings** by selecting the specific hardware device after it has been added under the desired system in the Navigation Menu.
- When assigning jumper colors, **Install Settings**, or **Operation Settings**, only the first hardware device is selected by default. When changing a jumper color or setting for all hardware devices of one type, ensure to press *Select All Rows* in the left window before changing the setting.

↑ Setup > Systems > Down Force > Hardware > Down	5.4 mph & IIII	11:23 pm 😲 ᠬ>	
Configure Down Force Sensor Settings		STI	EP 2 🔹 🔹
Location	Edit settings for selected modules		
Row 1	Sensor Type	72586	6 Sensor
Row 2	Calibration Offset		1,939
Row 4	Sensor Active		Enabled
Row 5			
Row 6			
Custom Select 🚔 Deselect All Rows 🛞			
Back	Save and Finish	\oslash	

 Ensure to select the correct module Mode (e.g. Select vApply Module / Rate Control Module HD Mode if adding a vApply or Rate Control Module to system with vApplyHDs).



Alerts

↑ Setup > Systems > Set	eding		\triangleright	5.4 mph & IIIII	11:24 pm 👎 ↔
Settings 🕻	>	Corn Alerts 🚸		▲ Implement	
Corn Alerts				Seeding	-
Population Alert Limit	1,000			Hardware	•
Population Adjustment	500 seeds/ac	,			
Seeds to Average	300			Nitrogen	
Population Failure Limit	80 %			Closing	
Singulation Alert Limit	98.5 %	Make a selection from the menu on the left to edit your settings here.		Down Force	
Spacing Alert Limit	95.0 %			Insecticide	
SRI Alert Limit	20			Depth	
				•	
Restore Defaults 🥏				🔒 Ho	me

Use the tab at the top of each system screen to view the crop-specific alerts for that system. Some $$84\,\mathrm{of}\,138$$

alerts are adjustable by default, others require the corresponding hardware to be added first. It is advised to add all system hardware before configuring alerts for ease of use. Alerts are saved to the specific crop.



Some alerts contain both **Alert** and **Failure** limits. The 20|20 will display a popup notification when alert limits are reached, and will perform the action selected for **Failure Action** when failure limits are reached. See **Display** in the **Settings** section of this guide for details on changing alert sounds.

🗘 ТІР

Many systems will have a **Population / Rate Adjustment** in the left window of Alerts. Change this value to determine the amount that the + (rate) / - (rate) buttons on the system control screen will use.

🗘 ТІР

Many systems will have a **Population / Rate Alert Limit** in the left window of Alerts. Change this value to determine the scale that is shown on the right of the DMC.

Diagnose

The **Diagnose Menu** is used to identify and troubleshoot hardware device failures and configuration issues in the 20|20.

Use the following colors to determine device status on the Diagnose screen.

- Green : Device is working correctly. Communications are good.
- Yellow : Device or sub-component is not 100% functional.
- Red : Device has failed, or is expected and not detected.
- White : Device is detected but not expected.
- Black : Device has been disabled by the user.
- Grey : Device is finishing detecting or unreachable.
- Teal : Device is updating firmware.

Landing Screen

The Diagnose Landing Screen displays an overview of overall Implement and Cab system health.

↑ Setup > Dia	gnose		Ð	2.7 mph ⓒ IIIII ☆ Systems	11:26 pm
PLANTER				Y Diagnose	•
	Seeding >	Down Force >	Closing >	Diagnose	
	Good 16Action Required 6	Good 9Action Required 5	Good 13 Good 13	Tractor	
	Depth >	Insecticide >	Nitrogen >	Planter	
	✓ Good 6		Good 13Action Required 1	Connectivity	
	Row Cleaner >	Implement >		System Schei	matic
			J	Event Log	
TRACTOR					
				Calibration	IS ►
	Good 5			🔅 Settings	
D	etailed Log 🚦	Rese	t Modules $ otal$	n Hor	me

Unexpected Hardware

↑ Setup > Diagnose			\bigcirc	4.8 mph	11:26 pm
Row Cleaner >	Implement >			X Diagnose	•
TRACTOR	_			Tractor	
Tractor >				Planter	
	J			Connectivity	
UNEXPECTED HARDWARE Hardware has been detected but is not configu	ured to a system.			System Schen	natic
🔿 vDrive 6 🖷 Tan	k Pressure Sensor 2	Dual Pressure Module 2		Event Log	
\ SpeedTube 3				Calibrations	
System Schematic 📏	Co	nfigure in Systems $ ight angle$		🔅 Settings	
Detailed Log 🔒		Reset Modules Ә		🔒 Hom	ıe

Scroll down on the Diagnose Landing Screen to view a list of all **Unexpected Hardware**.

Unexpected hardware is defined as any CAN / Ethernet Module or Hardware device which the 20| 20 detects but has not been configured by the user. Press *System Schematic* below to navigate to the System Schematic, or press *Configure in Systems* to navigate to the Systems Landing Screen.

Detailed Log

Press *Detailed Log* at the bottom of the Diagnose Landing Screen to enable a system log which records all CAN traffic and other data related to 20|20 operation for 60 seconds, after which recording is automatically disabled.



Precision Planting Product Support may require a detailed log when assisting the user with advanced troubleshooting. Detailed logs may be exported to an external USB drive. See **Export Data** in the **Settings** section for more details.



88 of 138

Reset Modules



Press *Reset Modules* at the bottom and confirm on the popup to break and reestablish all CAN communication and daisy chain identification. This function is often used as a troubleshooting tool for communication issues.

(!) IMPORTANT

Due to programming changes for sprayer and seeder compatibility, after pressing *Reset Modules* or power cycling in software versions 2023.1.0 and above, if a daisy chain break is present in the physical harnessing, all components after the daisy chain break will display red on the diagnose page. The break must be addressed before implement functionality is restored.

Cab

↑ Setup > Diagnose > Tract	or			Ð	5.4 mph	11:27 pm
TRACTOR	Ó				🔀 Diagnos	se 🔻
	đa				Tractor	•
					- Ether	rnet Switch
					Sield Mode	View ule
DBM >	🗠 Cab Control Mo	odule >	FieldView Module >		📮 10" D	Display
♦ GPS >	- Ethernet Switch	ı >	10" Display >		📮 16" C	Display
16" Display >					Cab (Mode	Control ule
Detailed Log 👂		l	Reset Modules $ \mathcal{D} $		n !	Home

The **Cab** section of the diagnose menu will share the same name as the Cab profile that is selected in **Equipment**. A graphic of the Cab and all devices / modules that are installed on it will be displayed.

Navigate to the desired system by pressing it in the center or the Navigation Menu.

DBM

DBM diagnostics are located under the Cab.

A Setup ► Diagnose ► Tractor	D	5.4 mph 11:27 pm ⓒ ⅢⅢ ◆ ↔→ ☆ Systems		
Hardware Version 2025.100.106	DBM Voltages Vehicle 13.1 Key Switch 13	BBM Health Battery Good Temperature Good MPC 311		 ★ Diagnose Tractor ▼ DBM
20 20 CAN Bus A Usage % 15.0 Rx Error % 0.0 Tx Error % 0.0	20 20 CAN BL Usage % 13.0 Rx Error % 0.0 Tx Error % 0.0	20 20 CAN Bus C Usage % 0.0 Rx Error % 0.0 Tx Error % 0.0		 Ethernet Switch FieldView Module
20 20 CAN Bus D Usage % 0.0 Rx Error % 0.0	OEM Bus A Usage % 0.0 Rx Error % 0.0	OEM Bus B Usage % 0.0 Rx Error % 0.0		10" Display16" Display
Tx Error % 0.0	Tx Error % 0.0	Tx Error % 0.0		Cab Control Module
Detailed Log 💡		Reset Modules $ \overline{\!\mathcal{O}} $		🟫 Home

- Version Software version
- DBM Voltages : Constant and key switch power from power supply to DBM.
- DBM Health : Battery and Temperature status, and Missing Package Correlation [MPC]. A rapidly climbing MPC value indicates CAN communication issues, such as damaged hardware or harnessing.
- CAN A / B / C / D : Displays network usage and percentage of errors in CAN packets sent / received. If usage values exceed 80%, add another CAN network to the implement.
- OEM BUS A / B : Combine mode only. Indicates network usage and percentage of errors in CAN packets sent/received.

Ethernet Switch

Ethernet switches will be displayed on the Diagnose screen under Cab or Implement depending on where they were configured in **Equipment** setup.



- Voltage : Displays supply voltage to the Ethernet switch.
- Port 1-5 : Displays POE status for the indicated Ethernet port.
- Switch CAN A / B / C : Displays network usage and percentage of errors in CAN packets sent / received for each CAN network generated from the Ethernet switch. If usage values exceed 80%, add another CAN network to the switch.

FieldView Module

If using a FieldView module [FVM] to connect to the Climate Corporation FieldView cab app and the FVM has been configured as an Ethernet module, FieldView diagnostics and controls will be displayed in the center screen after selecting FieldView Module in the Navigation Menu.



Use the indicator light on the FVM to diagnose connectivity issues. See **Indicator Light Overview** in the **General Overview** section of this guide for more details.

🗘 тір

If experiencing connectivity issues between the FVM and iPad, it is often necessary to change the charging and data transfer cable that connects the FVM to the iPad. There are several guidelines for selecting the correct cable.

- Ensure that the cable is non-counterfeit **MFI Certified**. This is the only supported cable type.
- For iPads with a USB-C charging port, ensure that the charging cable is rated for data transfer in addition to power charging.
- Ensure to use the shortest cable length possible from FVM to iPad. Data transfer issues increase with cable length.

Config Changes

Enable this setting to allow FieldView to make configuration changes in the 20|20.

() IMPORTANT

Enabling config changes will allow FieldView to push any changes to the 20/20. If a configuration change is made in the 20/20, but not in FieldView, this may result in operation where the 20/20 appears to be deleting configuration details such as tank mix, hybrids, prescriptions, etc. Ensure that any changes made in the 20/20 are also made in the equipment profile equivalents on FieldView as well.

Shared Swath

Enable this setting to allow swath sharing between two implements in the same field using FieldView.

Live View Only

Enable this option if using Panorama to send field map data to a FieldView account. Enabling this option will prevent the 20/20 from saving data on the FVM SD card. Maps will still build on the cab app.

Unpair FieldView Account

Unpairs a connected FieldView account.

Delete FVM SD Card Data

Deletes all data from the SD card in the FVM. This function will not delete data from the 20|20.

Rebuild FVM Fields

Uses field data on the 20|20 to rebuild FVM SD card data. The FVM will then sync the rebuilt data to FieldView.

Display

10" and 16" displays will appear on the Diagnose screen under Cab if configured correctly in **Equipment** setup.



CCM connection status is displayed. Only one display may have a CCM connected. The CCM will be automatically detected.

Cab Control Module

The CCM will be listed below the display to which it is connected.



On / Off position for all switches is displayed.

GPS

GPS diagnostics are located under the Cab. GPS will be displayed in red until proper GPS communication is established with the receiver.

() INFO

If GPS is configured on the Implement in Equipment setup, GPS diagnostics will be listed under the Planter on the diagnose screen.

A ► Setup ► Diagnose ► Tractor ► GPS					11:28 pm
GPS STATUS				DBM	
Fix Quality Enhanced	Baud Rate 38400	Communication Quality 100 %	:	— Etherne	t Switch
Satellites In View 13	ндор 0.60	Reported Heading 179		FieldVie Module	ew
Average 13 Coordinates	Speed	Time		📮 16" Disp	blay
Latitude 40.35990 Longitude - 89.92127	Reported 5.37 Calculated 5.3	UTC Wed Mar 5 05:28:27 GMT	2025	📥 Cab Cor Module	ntrol
NMEA MESSAGES RECEIVED				🔶 GPS	
 ⊘ GGA 5 Hz 	 ⊘ RMC 5 Hz 	 ⊘ VTG 5 Hz 		Planter 💌	
Detailed Log 🚦		Reset Modules $ \mathcal{D} $		🟫 Hor	me

- Baud Rate : Measures communication speed between the GPS receiver and 20|20. A rate of 38400 is recommended for Precision Planting systems.
- Fix Quality RTK is recommended for all Precision Planting control systems.
- Satellites in View / Average : An In View value lower than the Average value may result in reduced performance.
- HDOP Horizontal Dilution Of Precision. Values exceeding 1 may result in lower performance.
- Reported / Calculated Speed : Difference between these values may cause control issues.
- NMEA Messages Displays the rate per second that the GPS receiver is sending the required NMEA strings to the 20/20. All Precision Planting Systems require 5hz.

() IMPORTANT

Precision Planting products require **only** GGA, RMC and VTG strings at 5hz. If the third-party receiver is configured to output a different set of NMEA strings or a different frequency, control issues and diagnostic information will be affected. Check for correct NMEA output (and other GPS diagnostics) whenever control issues occur or information does not display correctly on the diagnose screen.

Speed diagnostics are also displayed on this screen. Scroll on the center to view Radar speed / state and primary speed settings.

Implement

↑ Setup > Diagnose > Plan	ter			\triangleright	\mathbb{D}	5.4 mph & IIII	11:28 pm ∳ ↔→
PLANTER						Planter 📥	-
<u> </u>						Seeding	
						Down Force	
<i>b</i>						Closing	
			A CONTRACTOR			Depth	
PDM 1	2	3 4	5	6		Insecticide	
						Nitrogen	
Seeding >	Down Force >		Closing >			Row Cleane	r ▶
Depth >	Nitrogen >		Row Cleaner >			Implement	
Detailed Log		R	eset Modules 긽)		🔒 Hon	ne

The **Implement** section of the diagnose menu will share the same name as the Implement profile that is selected in **Equipment**. A graphic of the implement and all devices / modules that are installed on it will be displayed.

Navigate to the desired system by pressing it in the center or the Navigation Menu.

Systems

A list of all hardware devices configured on the selected system will be displayed under the graphic in the center and in the Navigation Menu.

↑ Setup > Diagnose > Planter > Seeding	\mathbf{b}	5.4 mph 11:28 pm ⓒ ⅢⅢ
PLANTER		Planter -
		Seeding -
		SRM Seed Sensor
		🔔 mSet
		Flow Reducer
PDM 1 2 3 4 5	6	Flow Reducer Motor
		🕒 Vacuum Sensor
Flow Reducer Motor > SRM Seed Sensor > Flow Reducer Motor > Vacuum Sensor > Vacuum Sensor > Vacuum Sensor >	,	🧳 vDrive Primary
		Down Force >
Detailed Log 🗧 Reset Modules 🥏		🚹 Home

Press on the desired device to view a detailed diagnostic chart for that device.

Standard Hardware Diagnostics

A chart showing device health row-by-row for the selected hardware device will be displayed.

n rh Set	A → Setup → Diagnose → Planter → Implement → SRM				\triangleright	5.4 mph 1 & IIIII	1:29 pm
		Supply (V)	Implement Bus CAN Errors	Local Bus CAN Errors		Down Fo f se	
PDM	\oslash	13.2	0 %	0 %		Closing	
1	\oslash	13.4	0 %	0 %		Denth	
2	\oslash	13.6	0 %	0 %		Depth	Þ
3	\oslash	13.5	0 %	0 %		Insecticide	
4	\oslash	13.3	0 %	0 %			
5	\oslash	13.5	0 %	0 %		Nitrogen	Þ
6	\oslash	13.5	0 %	0 %		Row Cleaner	
							Ŧ
						U SRM	
						€ SmartFir	mer
		Detailed Log 🚦	Rese	et Modules <i>Ə</i>		n Home	

- SRM : View supply volts and implement / local (row) CAN errors.
- Ride Quality Sensor : View Good Ride readings from SRM accelerometers.
- Gyro / Implement Motion Sensor : View turn rate and acceleration readings.
- Lift Switch : View switch position and calibrated lift / lowered status.

(i) NOTE

SRM diagnostic details are accessible from **Implement (Default) System** on the **Diagnose** menu.

Refer to the appropriate system-specific operator's guides for diagnostic information on all other hardware devices.

Connectivity



The **Connectivity** section of the Diagnose menu displays Wi-Fi and Passmaster connection status. Press on either option in the center or Navigation Menu to view each connection details.

Wi-Fi

Displays network name and hardware MAC address.



Passmaster

Displays connected Panorama operation name and connected server, as well as DBM serial number / name and active field name. When multiple DBMs are connected to a Panorama operation, each DBM and information regarding its active field will be displayed in the **Connected DBMs** table below.



System Schematic

The **System Schematic** displays a schematic overview of all Ethernet and CAN modules / devices connected to or configured in the 20/20. Use the System Schematic to identify setup issues and damaged modules / harnessing and determine troubleshooting procedures.



The icon to the left of each device name represents the health of that device. The outline around the device name indicates the health of the devices connected to it. If there are both red and white devices connected, the outline will be red.

♠ Setup > Diagnose > System Schema	tic 🖸	5.4 mph 11:31 pm ⓒ IIIII ↔ ↔→ ☆ Systems →
		🔀 Diagnose 🗸 🗸
Ethernet Switch Port 1 102000089	FILTER ▼ Good 87	Tractor →
10" Display Port 1 40108647	Failed 0	Planter →
FieldView Module Port 5 60213699	◆ Action Required 12	Connectivity >>
Cab Control Module		System Schematic
- ≁ f Bus A	C Updating 0	Event Log
SRM PDM	A Unexpect 13	Calibrations
Lift Switch PDM Implement		Settings
Detailed Log 🚦	Reset Modules $ otal$	🟫 Home

104 of 138

For any device that has a dropdown arrow next to its icon, press that arrow to expand the schematic to show all connected devices. Alternatively, press *Expand* in the upper right corner to immediately expand the entire schematic.



Press the filters on the right side to filter all modules by health. Any filter which is active will have a blue-green outline. Press any active filer to deactivate it.

Using the Schematic

🗘 тір

Use the following tips when diagnosing system issues using the system schematic.

- Red devices typically indicate damaged / disconnected modules or harnessing.
- White devices typically indicate incomplete system configuration.
- An incorrect number of CAN bus devices (e.g. SRM) with some displayed in green, white and / or red typically indicates incorrect **Module** setup.
- Yellow devices typically indicate that a device is uncalibrated, underpowered, or commanding / being commanded outside accepted parameters.

 It is possible to use a second display connected to the DBM to view the system schematic while performing setup on the primary display to streamline the setup process.

Event Log

The **Event Log** contains a list of notifications that the 20|20 has generated for the user. Use the search filter at the top to search events by name.

↑ Setup > Diagnose > Event Log	0.0 mph 😵 IIIII	2:40 pm ↔•>
	Equipment	
Q Search	👫 Systems	
Location PDM		
Start Time 2/26/25 4:15 PM	X Diagnose	
Description The Gyro has not been zeroed. The system Gyro is used for rate control turn compensation, and will not be operational until a zero has been completed.	Tractor	
Event 12004	Planter	
No work state sensor has been configured		
Start Time 2/26/25 4:15 PM	Connectivity	
Description No work state sensor has been configured to determine frame position. Control systems will not be operational.	System Schen	natic
Event 12000	Event Log	
No coverage source configured		
Start Time 2/26/25 3:50 PM		
Description No application system is configured to draw coverage on the coverage map. Swath control will	Calibrations	
Dismiss All Notifications 🛞	🔒 Hom	ne

Typical events include, but are not limited to:

- Uncalibrated devices : Any device which is not calibrated, but must be in order to function.
- Misconfigured devices : Any device which was configured improperly.
- Damaged devices : Damage is detected on connected devices (e.g. internal DBM battery).
- Missing devices : Devices were set up, but not detected.
- Incompatible setup : Incompatible devices (e.g. wrong load cells for the row unit selection) or an unusable system setup was configured.

Calibrations

The **Calibrations** menu is used during first time setup to prepare all systems for proper 106 of 138

functionality, to recalibrate hardware at season start, after installing new hardware devices, and when changing products or zeroing sensors.

↑ Setup > Calibrations		\triangleright	5.4 mph 11:34 pm È IIIII ↔ ↔>
TRACTOR GPS Offset Check Confirm the entered Vehicle & Implement GPS measurements against the actual GPS output location	Radar Calibration > Calibrate radar speed		System System Calibrations
SEEDING			Tractor
Manual Test > Manually test seeding system			Seeding Down Force
DOWN FORCE			
Zero Load Sensors > Set the Down Force Sensor offset value	Manual Test > Manually test force system		Closing Depth
	Manual Test		Nitrogen
Set the FurrowForce Sensor offset value	Manual Test > Manually test force system		A Home

A master list of available calibrations will be displayed on the **Calibrations Landing Screen**. Filter this list by pressing on the options displayed below **Calibrations** in the Navigation Menu.

This guide will detail calibrations common to all Cab / Implement combinations. Refer to systemspecific operator's guides for information on running other system calibrations.

(i) NOTE

Sensors such as load cells and EM FlowSense are not zeroed on the diagnose screen. Use **Calibrations** to zero sensors.

Cab Calibrations



Press (Cab Name) in the Navigation Menu to perform a GPS offset check or calibrate radar.

GPS Offset Check


Run through the calibration wizard to perform the offset check following the on-screen instructions. Ensure that the application points / seed exits are even with the placed markers on step 1 and step 4.

🖓 ТІР

This test may be easier to perform with a spotter to determine that the application points / seed exits are even with the placed markers.

Resulting differences of less than 12 inches are recommended, but best control will be experienced with differences as close to 0 as possible. Higher differences will result in less accurate swath timing.

Precision Planting Product Support recommends to repeat this test and / or remeasure implement dimensions to achieve more accurate results before using start / stop timings and application offsets to fine-tune control. Support also recommends to perform this check at every season start.

5.4 mph 11:34 pm A ► Setup ► Calibrations ► Tractor ► Radar Calibration (X) IIII **Prepare to Calibrate** STEP 1 Running this test may result in implement motion, motors spinning or product being applied. Maintain a safe distance! A DESCRIPTION ST CHECKLIST GPS Connected To calibrate the Radar, the vehicle must be driving straight forward at a constant speed of 4.00 mph or More than 300 ft of straightaway greater for about 300 ft. Good GPS Reception is Moving at a speed of at least 4.00 mph at start required! Cancel 区 Continue >

Run through the calibration wizard to set pulses / foot for the radar. Good GPS signal is required. Once the bar fills, the calibration is complete. Navigate to **Setup > Diagnose > (Cab name) > GPS** and scroll on the center screen to confirm that GPS and Radar speed match. Perform the 109 of 138

Radar Calibration

calibration again if necessary.

↑ Setup > Diagnose > Tractor	→ GPS			$\mathbf{\Sigma}$	5.4 mph & IIII	11:35 pm ᢤ ↔>
Coordinates : Latitude 40.36128 Longitude -89.92117	Speed Reported 5.37 Calculated 5.3	8	Time UTC Wed Mar 5 05:35:31 202 GMT	25	🔲 DBM	net Switch
NMEA MESSAGES RECEIVED					Field\ Modu	/iew le
	✓ RMC		✓ VTG		🔲 10" Di	isplay
5 Hz	5 Hz		5 Hz		📮 16" Di	isplay
SPEED					📥 Cab C Modu	ontrol le
✓ Radar Speed	🕑 Radar Stat	te			🧼 GPS	
5.0 mph	Disabled		Good			
⊘ Primary Speed	Speed Sou	ırce			Planter	
GPS	GPS				Connectivit	y ≻
Detailed Log			Reset Modules $ \widehat{\!\mathcal{O}} $		† H	ome

Implement Calibrations

↑ Setup > Calibrations > Implement		\triangleright	5.4 mph 😵 IIIII	11:35 pm ♦ ♦••
			Tractor 🔺	
Gyro Calibration >	Lift Switch Calibration >			
controllers	Set the lifted and lowered work state position for the implement		Seeding	
			Down Force	
			Closing	
			Depth	
			Nitrogen	
			Row Cleaner	
			Implement	
			🔅 Setting	•
			Gettings	
			n Ho	me

110 of 138

Press the (Default system name) system to calibrate the Gyro / IMS or calibrate a height sensor.

Gyro / IMS Calibration

↑ Setup > Calibrations > Implement > Gyro Calibrations	5.4 mph & IIIII	11:35 pm 🔶 🖘	
Prepare to Calibrate		STEP	1 • • • •
Running this test may result in implement motion, motors sp	pinning or product being applied. Maintain a	safe distance!	
DESCRIPTION This calibration will require you to completely stop your equipment. After, you will be able to evaluate if the calibration zeroed the gyro properly by driving forward and turning.	S ■ CHECKLISTImplement connected to vehicle		
Cancel 🛞	Continue >		

Run the calibration wizard to zero the gyro or IMS. Follow the on-screen instructions to zero the sensor when necessary.

Lift Switch Calibration

↑ Setup > Calibrations > Implement > Lift Switch Ca	5.4 mph	11:35 pm ᢤ ↔>	
Prepare to Calibrate		STEP 1	
Running this test may result in implement motion, motors sp	inning or product being applied. Maintain a	safe distance!	
DESCRIPTION This test will perform a Lift Switch Calibration process to determine the correct Lifted and Lowered percentages to meet the desired range.	SE CHECKLIST	ipplicable)	
Cancel 😣	Continue >		

Run the calibration wizard to perform a three-point calibration of a lift switch. Set **Raised, Lowered and Engagement** height on the different steps.

↑ Setup > Calibrations > Implement >	Lift Switch Ca	libration		5.4 mph & IIII	11:36 pm 🔶 ↔
Calibration Successful				STEP 5	••••
LIFT SWITCH CALIBRATION To see if the calibration was completed, raise	and lower the impleme	ent. Press Done if calibr	ation was successful	or press Resta	rt.
	Position		Work State		
PDM 🛇	100 %		Lowered		
Recalibrate 🥏			Done 🧭		

Use step 5 to raise / lower the implement and confirm correct position readings.

Settings

The **Settings** menu is used to import / export / delete 20|20 data, connect to Wi-Fi or Panorama, and adjust user preferences.



The **Settings Landing Screen** displays basic system information such as software version and active connections.

Software Update



Use the Software Update screen to update via Internet or external USB drive.

Select either option in the left window to perform either update process.

Wi-Fi Update

Precision Planting hosts commercial release software updates online free of charge. Connect the 20/20 to the Internet and select the desired software version in the right window to download and install the update. The 20/20 will restart after downloading to finish the update.

USB Update

The most recent versions of commercial and limited release software may be downloaded from 2020.ag and placed on the root drive of an external USB drive. The software update file must not be placed into a folder on the USB drive. Connect the USB drive to the USB port on the display. Press *Install from USB* and select the software update from the popup to perform the update.

🖓 ТІР

In some cases, software updates may fail. In these cases, it is often necessary to try the update using a different, higher quality USB drive. Many older or lower quality USB drives have weak internal soldering and inferior components which may cause update issues.

Boot Software

In rare occurrences, software mismatches between display / DBM, device crashes, or other update issues may occur. In these cases, it is often necessary to use the boot software process.

Precision Planting Product Support recommends the following process to increase success rate for boot software.

 Download the desired version of boot software by visiting 2020.ag and clicking either commercial or limited release. Then scroll to the bottom of the page and click View complete list of changes by release. Download the desired boot software version from the list and place it onto a USB drive using the same instructions as standard software. Ensure that the file does not have spaces or parentheses in the file name.

() INFO

The 20/20 cannot boot to the version of software that is currently installed. For example, if 2025.0.0 was the last installed version, download 2024.0.2 boot software

- 2. Unplug the display and implement from the DBM and press the power button on the back of the DBM. Wait until the DBM LED goes out.
- 3. Connect the USB drive to the USB port on the DBM. Then press the power button on the DBM to turn it on.
- 4. Wait for the following light sequence to complete.

LED	Description
Solid White	Powering on
Solid Yellow	Initializing
Flashing Yellow	Reading boot software
Solid Yellow	Initializing
Flashing yellow	Software Update in Process
Solid Yellow	Post update Finalizing

LED	Description
Solid Blue	Fully updated to 25.0.x or older software
-or-	
Solid Green	Fully updated to 25.1.x or newer software

5. Disconnect the USB drive from the DBM.

- 6. Connect the USB drive to the USB port on the Display. Then connect the display to the DBM.
- 7. The display will go through a boot up sequence as it reads the boot software and eventually load the Home screen. Then remove the USB drive from the display and resume normal operation.

() INFO

An FVM may also be updated using boot software in troubleshooting cases. Disconnect the FVM from the DBM and iPad, then wait for the FVM LED to go out. Connect the USB drive with boot software loaded to the USB port on the FVM, then reconnect the FVM to the DBM and wait for the FVM light to go purple.

🗘 тір

Advanced Users

Boot software is the same file as a standard software update file. Only the file name is different. Any software update file may be renamed to:

2020Gen3-full

This will "convert" the standard update file to boot software.

Connectivity



Use the **Connectivity** screen to connect to Wi-Fi or pair the 20/20 with a Panorama operation.

Connecting to Wi-Fi

Press *WiFi network* in the right window and select the desired network in the left window. Enter the network password using the popup keyboard. Press *Scan* to refresh the list of available networks. Press *Other* to manually enter network name. Press *Forget* on a saved network to disconnect and forget password.

(i) NOTE

For security reasons, the 20|20 will only connect to a password-protected Wi-Fi network.

If the 20|20 will not connect to the desired network, try to connect to another network (e.g. a phone hotspot) for testing purposes to determine if the issue is with the network, or with the interior hardware of the 20|20.

Connecting to Hardwired Internet

A hardwired internet connection will typically be the most reliable and fastest source of Internet connection.

To connect the DBM directly to an Internet access point, connect a third-party USB-A to Ethernet $^{117}_{117}\,\mathrm{of}^{138}_{138}$

adapter to the USB port on the DBM. Then connect the adapter to the Internet access point using an Ethernet cable. Do not connect the Internet access point to the DBM using the POE ports.

Pairing with a Panorama Operation

Select *Paired Operation* in the left window and press *Pair Device* to run the pairing wizard.

↑ Setup > Settings > Connectivity		\triangleright	0.0 mph 2:40 pm ⓒ IIIII ↔→ ∑ Systems ▶
Connectivity	Paired Operation		X Diagnose
Network Settings WiFi Network None	You have not set up Panorama on this device yet. Pair device to get started.		Calibrations
Panorama Settings			🤃 Settings 🛛 🔻
Paired Operation			Software Update
			Connectivity
			Import Data >
			Export Data →
			Display
	Pair Device >		🔒 Home

Ensure that step 1 displays a Hostname in the bottom right. If it does not, the 20|20 is not connected to Internet or Panorama servers are inoperable. Then press *Continue*.

↑ Setup > Settings > Connectivity > Pair Device	0.0 mph 2:41 pm € IIIII «··>
Pairing Instructions	STEP 1 • • •
DESCRIPTION This process will guide you through the steps to pair your 20 20 to your Panorama operation.	 CHECKLIST Working Internet access to your 20 20 from a dedicated WiFi hotspot or cellular phone Access to a web browser to complete the pairing process
Hostname > sync.panorama.ag Cancel S	Continue >

A pairing code and QR code will be generated. Scan the QR code in the Panorama app, or enter the pairing code on the Panorama website by clicking **Add Device +** on the **Devices** tab under **Manage Operation**.



119 of 138

Import Data



Use the **Import Data** screen to import different types of data from an external USB drive or Panorama into the 20/20 or to restore configuration using an internal backup.

Configurations, Maps, and other monitor data

For configurations, maps, and third-party or 20/20 Gen 2 data; connect an external USB drive with the desired files loaded and press the desired option. A popup with all files of that type which are loaded on the USB drive will open. Select the desired files to import them.



Importing **Device** and **Display Configurations** will replace the active configuration. Any unsaved changes will be lost. Save and / or export the active Device or Display configurations before importing.

Importing an **Account Configuration** will erase all saved Equipment profiles, display layouts, Clients / Farms / Fields, and field map data. Export all desired elements before importing.

Prescriptions and Boundaries

For prescriptions and boundaries, connect an external USB drive with the desired files and select the desired option. A popup with files of that type which are loaded onto the USB drive will open. Select each of the desired files, or press *Select All* in the lower right, then press *Import*.

🛉 + Setup + Settings + Impo	ort Data		$\left \right\rangle$	0.0 mph	3:02 pm
Account Configuration >	Panor	ama Account Configuration >		 Settings 	
Import Prescription				Car	ncel 🗵
Force All Ext	erior Polygons	Normal Proc	essing N	lode	
2025_00_Plant_00.2020	344ffbf1-abfd-4077-927a- ab02b23347cc.2020	35609b8d-bb11-4f24- bf0a-0df45ba946f6.2020	66c ae1f-	388ba-2d6e-40 7e65c3ace23f.∶	93- 2020
b15c1368-1b7b-40bb- aeab-4fc71026ffa7.2020	b5e4748b-25a0-4ece- a74b-47d8b35de18e.2020	exported_account_config. 2020	ехро	rted_device_co 2020	nfig.
f4455dab-4ee4-41d9-8a	Northeast 7_Corn Seed_20230415 (2).shp	NW 62_Corn Seed_20230415 (2).shp			
Select	All 🗹	Imp	ort 😃		
Restore Configuration Reload all configuration from a previous				About 🚽	

(i) NOTE

The **Force All Exterior Polygons** option is a troubleshooting measure intended for use when experiencing improper prescription / boundary control. Delete the originally imported file before using this option.

() INFO

All prescriptions and boundaries must be in shape file format (or .2020 file format) to import into the 20|20. A shape file consists of 3 files with the same name but a different file extension (.shp + .shx + .dbf). For example, to import a prescription named "Seeding", the user must to generate the following files from a third-party program:

- Seeding.shp
- Seeding.shx
- Seeding.dbf

The user must then place those 3 files onto a USB drive, then import into the 20/20. The 3 files will show as 1 file in the popup.

If issues are encountered when importing prescriptions or boundaries, try using a different USB drive, or try importing only one shape file at a time.

Panorama Account Configuration

Press *Panorama Account Configuration* or select *Panorama Account* under **Import Data** in the Navigation Menu to import a Client / Farm / Field structure from a paired Panorama operation.

♠ Setup > Settings	▶ Import Data ▶ Panor	ama Account		mph Settings	•••>
DBM All				Software Update	
Field	Farm	Client	DBM		
10			30110241	Connectivity	
			30112206	Import Data	•
			30112206	Panorama Accou	unt
10.0			30112206		
1000			30119743	Export Data	
				Display	
				Region	
Sele	ect All 🗹	Clea	ar All 🛞	About	
	Import Sele	cted Fields 🔟		A Home	

The table in the center displays all fields and their associated Client and Farm, and the DBM which they were created on. This table may be filtered by DBM using the dropdown box at the top.

Restore Configuration

Press *Restore Configuration* to open a popup database of backup device configurations. The 20|20 will generate a backup of the active Equipment profile every time it is power cycled if there is not an existing backup in the last 24 hours. Select an entry from the database to load it.

	ort Data		Þ	5.4 mph	
Import				Ca	ancel 🛞
2024-02-27.device_config	2025-01-29.device_config	2025-01-31.device_config	2025-0	02-03.device_	_config
2025-02-05.device_config	2025-02-06.device_config	2025-02-07.device_config	2025-0	02-08.device_	_config
2025-02-10.device_config	2025-02-11.device_config	2025-02-12.device_config	2025-0	02-13.device_	_config
2025-02-14.device_config	2025-02-17.device_config	2025-02-18.device_config	2025-0	02-19.device_	_config
2025-02-20.device_config	2025-02-21.device_config	2025-02-24.device_config	2025-0	02-25.device_	_config
2025-02-26.device_config					
Reload all computation from a previo	us stanup.				

Using **Restore Configuration** will replace the active configuration. Any unsaved changes will be lost. If desired, save and / or export the active Device and Display configurations before importing.

Export Data



Use the **Export Data** screen to export different types of data to an external USB drive or to Panorama.

Account / Device / Display Configurations

Connect a USB drive, then press the desired option and use the popup keyboard to enter the desired name for the configuration. Press enter on the keyboard to export the configuration with the entered name.

Prescriptions / Boundaries

Connect a USB drive, then press the desired option in the center or under **Export Data** in the Navigation Menu to open a table which displays all files of the selected type saved on the 20|20.

★ Setup Settings Export Data Prescriptions				11:39 pm ᢤ ↔→
Name	Туре		Software Up	date
rd_vss_demo	Seeding		·	
insecticide_demo	Granular		Connectivity	
rd_liquid_demo	Liquid		Import Data	
			Export Data	•
			Field Map	Data
			Prescriptio	ons
			Field Boun	daries
Select All 🗹	Clear All 🛞		Display	
Export Selected	Prescriptions 🖞		n Ho	ome

Press each desired file in the table or press *Select All* in the bottom right, then press *Export Selected (File Type)* to export all selected files to the USB drive.

Field Map Data

Press *Field Map Data* in the center or under **Export Data** in the Navigation Menu to open a table which displays all field map data files.

↑ Setup > Settings > Export Data > Field Map Data					\triangleright	5.4 mph & IIII	11:39 pm 🔶 ↔	
Upload All -	Season	All 🝷	Pass All	•	dbm Ali	•	Software Up	odate
Field Name	Upload	Date	Data Size	Season	Pass	DBM	Connectivity	/
2-21-180	0%	01-01-70	656 kB	2025 Corn	Plant	30112285		
2-25-180	0%	02-26-25	56 MB	2025 Corn	Plant	30112285	Import Data	
Default Field	0%	01-01-70	99 kB	2025 Corn	Plant	30112285	Export Data	•
Test	0%	02-26-25	42 MB	2025 Corn	Plant	30112285		
1-29-180	0%	01-29-25	11 MB	2025 Corn	Plant	30112285	Field Map	Data
2-24-180	0%	02-25-25	42 MB	2025 Corn	Plant	30112285	Prescriptio	ons
2-5	0%	02-20-25	84 MB	2025 Corn	Plant	30112285		
							Field Bour	idaries
Select All 🗹 Clear All 😣			Display					
Export Selected Fields 🜵 Upload Selected Fields 🖂 Rebuild Selected Fields 🥏			l Fields $ \mathcal{D} $	1 He	ome			

Press each desired file in the table or press *Select All* in the bottom left. Press *Export Selected Fields* to export all selected files to a connected USB drive.

To export to Panorama instead of a USB drive, press *Upload Selected Fields* in the bottom center to export all selected files to a paired Panorama operation. Internet connection is required for Panorama upload.

To rebuild FVM fields, press Rebuild Selected Fields in the bottom right.

If exported files display on a desktop / laptop computer as .tmp files, then the export did not complete. Typically, this is due to a USB drive that is too small or low quality. Try exporting only one file, or try a higher quality USB drive.

Support Data

Connect a USB drive, then press **Export Support Data** to export data logs and all screenshots onto the USB drive. Typically, this will only be done in troubleshooting situations when requested by Precision Planting Product Support.



Display

Use the **Display screen** to adjust audio / visual settings, disable display alerts, or perform a touch screen test.



Press *Restart Display* in the bottom left to restart the display only. The DBM will not restart.

Press *Standby* in the bottom left to put the display into low power / sleep mode. The screen will stay dark until the user presses anywhere on it.

Brightness

Select *Display* or *LED Brightness* in the left window, then use the toggle in the right window to switch between automatic and manual brightness and the slider to increase / decrease manual brightness level. Automatic will utilize the photosensor on back of the display to dim or brighten the respective setting.



Sounds

Select a sound and / or volume in the left window, then select a sound for the setting or adjust its volume in the right window.

↑ Setup > Settings > Disp	lay		\triangleright	mph (Master + ++++++++++++++++++++++++++++++++++
Display Settings		Alert Sound		Setting
Alert Sound	Chime High	None	Buzz	Software Update
Alert Volume	0 %	Веер	Chime	Connectivity
Failure Sound	Ripple	Ring	Chime High	Import Data →
Failure Volume	0 %	Chime Low	Organ Low	Export Data →
Click Sound	Click 1	Ping	Yell	Display
Click Volume	0 %	Train	Gonna Blow	Region
Multiple Display Settings				About
Alerts and Alarms	Disabled	Ripple	Car Horn	Delete Data>
Restart Display	ə	Stand	by (A Home
		130 of 138		

- Alert : Sound played when a user-defined system alert threshold is reached or a hardware device is functioning sub-optimally.
- Failure : Sound played when a user-defined system failure threshold is reached ot when a hardware device has failed.
- Click : Sound played when a screen press is detected.

Mulitple Display Settings

Select the desired setting in the left window, then enable / disable **Alerts**, **Screen Jumps** or **Popups** in the right window. This will only affect the display that this setting is being adjusted on.

↑ Setup > Settings > Display			\triangleright	mph (Master •••
Display Settings		Alerts and Alarms		🔅 Setting s 🔹 🔻
Failure Volume	0 %	Enable or disable notifications on this 20 20 Display		Software Update
Click Sound	Click 1	Enabled		Connectivity
Click Volume	0 %			Import Data 🛛 🔸
Multiple Display Settings				Export Data >>
Alerts and Alarms	Disabled			Display
Screen Jump	Disabled			Region
Event Popups	Disabled			About
Touch Screen Test				Delete Data
Restart Display Ә		Standby 🕛		🟫 Home

Disabling these settings prevents the display from notifying the user of important diagnostic information. Disable these settings only if there is a second display connected to the DBM with all alerts/alarms enabled.

Touch Screen Test

Press *Touch Screen Test* in the left window and again in the right window to run the touch screen test.



Draw on the screen to confirm touch screen functionality. Press and hold on the screen for 5 seconds to exit the test.

Region

Use the Region screen to change to change 20|20 language, toggle units of measure from Imperial to Metric, or change time zone.



About

Use the **About** screen to view device information and disk usage for the DBM, display, and FVM (if connected).

↑ Setup > Settings > A	bout	$\boldsymbol{\Sigma}$	5.4 mph & IIIII	11:40 pm •••
About			€ Settings	•
Display			Software Upd	late
Software Version	2025.100.106		Connectivity	
Serial Number	40108647		Import Data	
Disk Usage	79.4 %			
IP Address	172.20.20.103		Export Data	
Display Base Module			Display	
Software Version	2025.100.106	Make a selection from the menu on		
Serial Number	30112285	the left to edit your settings here.	Region	
Disk Usage	0.0 %		About	
IP Address	172.20.20.1		About	
FieldView Module			Delete Data	
Software Version	2025.100.106		n Hor	me

(i) NOTE

If DBM disk usage exceeds 70%, performance may begin to slow. If disk usage exceeds 70%, back up and then delete field data. See **Delete Data** later in this section for more details. Display disk usage is typically in the 70-80% range.

The about screen also allows the user to view the EULA or release notes for the currently installed software version.

↑ Setup > Settings > A	bout	$\mathbf{\Sigma}$	D 5.4 mph 11:40 pm ℃ IIIII ◆ ↔
About Software Version Serial Number Disk Usage IP Address	2025.100.106 30112285 0.0 % 172.20.20.1		Software Update Connectivity
FieldView Module Software Version Serial Number	2025.100.106 60213699	Make a selection from the menu on	Export Data
Agreements Release Notes		the left to edit your settings here.	Region About
Advanced DBM IP Address	1v1 Debug Code 172.20.20.1		Delete Data →

Press Reset EULA to force the display to show it again on the next boot up.

Advanced Users Only

The About screen may also be used to enter a Debug Code if advised by Precision Planting Product Support, or to change to IP address of the DBM.

Delete Data

Use the **Delete Data** screen to erase data from the 20|20.

↑ Setup > Settings > Delete Data		\triangleright	5.4 mph & IIII	11:40 pm
I Field Map Data > Recorded .2020 files from field passes.	Prescriptions > Prescriptions from a .2020 file.		Software Upc	• late
Field Boundaries > Field boundaries from a .2020 file.	All Data >		Connectivity	
Reset Settings > Resets display layouts and sound back to factory	Factory Reset > Resets system configuration back to factory defaults.		Import Data	Þ
defaults. IIII Clear Local Data Cache →			Export Data	۲
Removes all cached field data and background imagery.			Display	
			Region	
			About	-
			🔒 Ho	me

Clearing Device Settings

Select *Factory Reset, All Data, Reset Settings*, or *Clear Local Data Cache* and confirm on the popup to erase the selected type of data. Deleted data is not recoverable.

() INFO

- Deleting **All Data** will erase everything from the Gen 3, including field map data, screenshots and the restore configuration backup table.
- Clearing the **Local Data Cache** is intended for use in troubleshooting situations and deletes data from the dispaly only. DBM data will not be erased.

Deleting Maps / Prescriptions / Boundaries

Press *Field Map Data, Prescriptions* or *Field Boundaries* in the center or under **Delete Data** in the Navigation Menu to open a table which displays all files of the selected type. Press each desired file in the table or press *Select All* in the bottom left. Press *Delete Selected (File Type)* to erase the selected files from the 20|20. Deleted data is not recoverable.

A ► Setup ► Settings ► Delete Data ► Field Boundaries			5.4 mph & IIII	11:41 pm
Name rd_boundary	Type Seeding		Export Data	
			Region About Delete Data	Ţ
			Field Map I Prescriptio	Data Ins
Select All 🗹	Clear All 😣		Field Boun	daries
Delete Selected Field Boundaries 🛞			n Ho	ome

Appendix A

Understanding Home Screen Metrics

Singulation - Measure of meter performance showing the percentage of seeds that are properly singulated - where the meter releases one seed rather than a skip or multiple.

SRI - Seed Release Index. SRI measures the consistency of seed spacing. It only takes into account properly singulated seeds so that skips and multiples are factored out of this measurement. It is a rolling average of the *Seeds to Average* value set in the seeding system alerts. The lower the number, the more consistent the seed spacing is. A theoretically perfect SRI score would be zero (0) and would indicate that every seed was placed in the exact correct position relative to its neighbors. Seed Release Index values over 32 mean that consistency of seed spacing is so erratic that it is considered to be random. Many factors, including meter type, meter performance, drive type, sensor location, ride quality, and seed characteristics may affect SRI. The expected SRI will be different for different planters with different meter and drive type combinations. Regardless of these differences, SRI commonly begins to have agronomic implications when it rises to 20 or higher. Because of this, the SRI button is configured by default to turn yellow when SRI reaches 20. This may be changed in the Limit Adjustments menu. Note that SRI on the planter will be higher than SRI on a MeterMax test stand

Down Force - This indicates the force acting on the gauge wheels. This is achieved by measuring 137 of 138

the pressure against the depth stop created when the gauge wheels push against and converting that pressure into pounds of pressure. This is accomplished with a load cell installed on the row unit. For information on setting down force controls, see the relevant operators guide.

Down Force Average - This displays the average measurement of all load cell readings on the planter over a given period of time. This time period varies depending on the down force system installed.

Margin - This is the lowest measured load cell reading in a given period of time on one row (varies with down force system installed). The Margin value displayed on the home screen Down Force button is an average of this value across all load cell-equipped rows on the planter.

Ground Contact - The percentage of time the system can confirm that the gauge wheels have met the depth stop, which generally indicates that the row unit is planting at the depth to which it has been set.

Skips / Multiples - This metric identifies the breakdown of improperly singulated seeds among skips and multiples.

Good Ride - The Good Ride metric displays the percent of time when ride quality is sufficient not to interfere with seed spacing. This measurement provides assistance in diagnosing spacing errors caused by rough row unit ride. It is primarily used to help maximize speed while maintaining good SRI performance. When SRI is high and good ride is high, slowing down may improve SRI performance.

Average Spacing - This metric indicates the average spacing of seeds in the seed trench. It is calculated by dividing a number of seeds by the distance traveled while planting those seeds. It is not an indication of spacing accuracy.